

# SCRAM Instructions

HW1 due tonight!

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Binary data

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13 Sept. 2019

fgets / scanf / etc.  
⇒ text / strings



Binary input :

getc , fgetc  
return 0-255  
or EOF (-1)

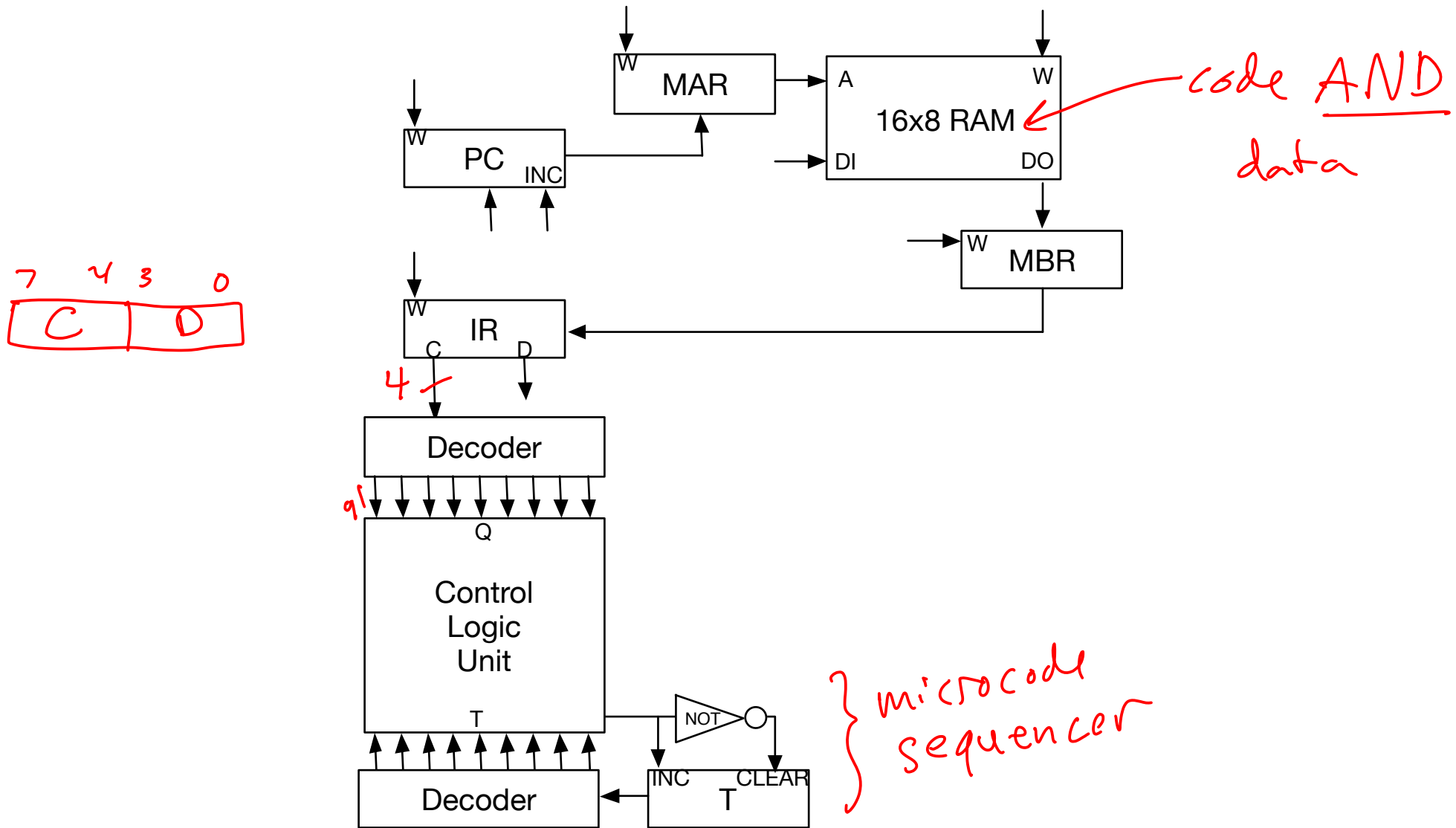
fread

# Reminder



- Fully work through a computer
  - circuit
  - assembly code
- Simple but Complete Random Access Machine (SCRAM)
  - every instruction is 8 bit
  - 4 bit for op-code: 9 different operations (of 16 possible)
  - 4 bit for address: 16 bytes of memory
- Background reading on web page
  - The Random Access Machine
  - The SCRAM

# Circuit (At This Point)



# Instruction Fetch



- Retrieve instruction from memory
- Increase program counter

<b>Time</b>	<b>Command</b>
$t_0$	$\text{MAR} \leftarrow \text{PC}$
$t_1$	$\text{MBR} \leftarrow \text{M}, \text{PC} \leftarrow \text{PC} + 1$
$t_2$	$\text{IR} \leftarrow \text{MBR}$

# l da

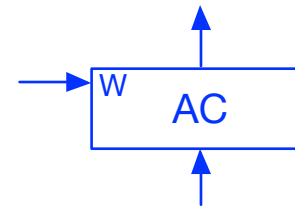
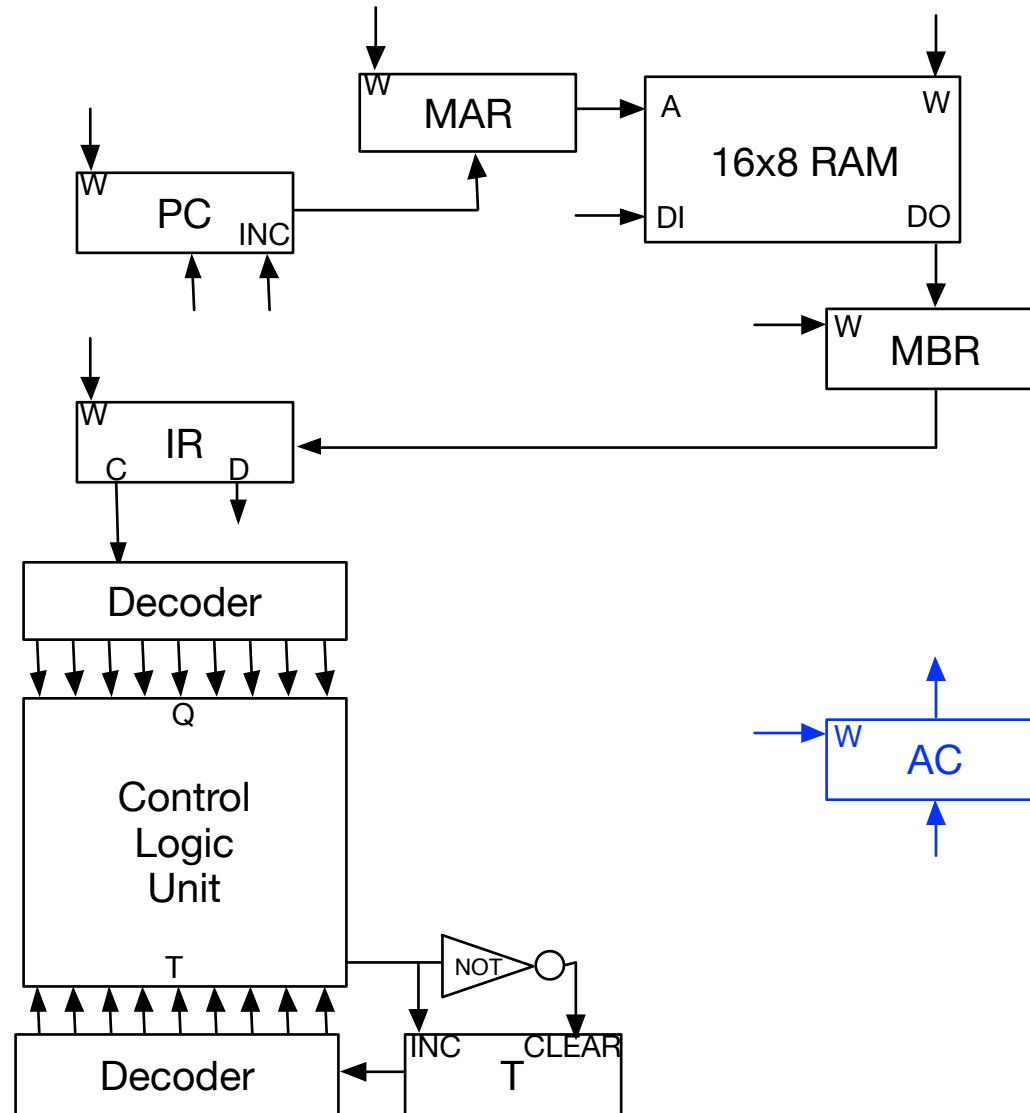
# Micro Program



- Load into accumulator

Op Code	Time	Command
q <sub>1</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>1</sub>	t <sub>4</sub>	MBR ← M
q <sub>1</sub>	t <sub>5</sub>	AC ← MBR, <i>end of microcode</i>

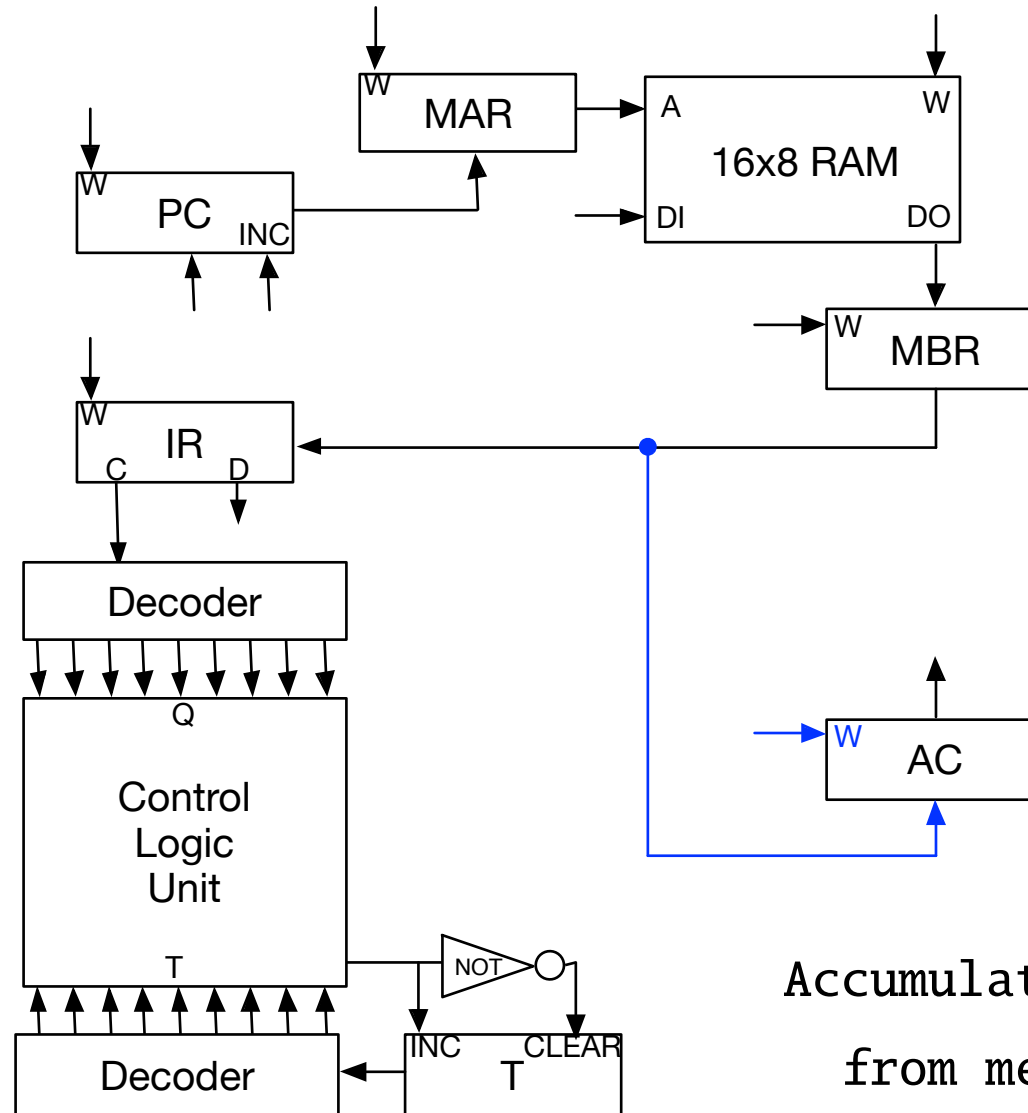
# Accumulator



*accumulator*



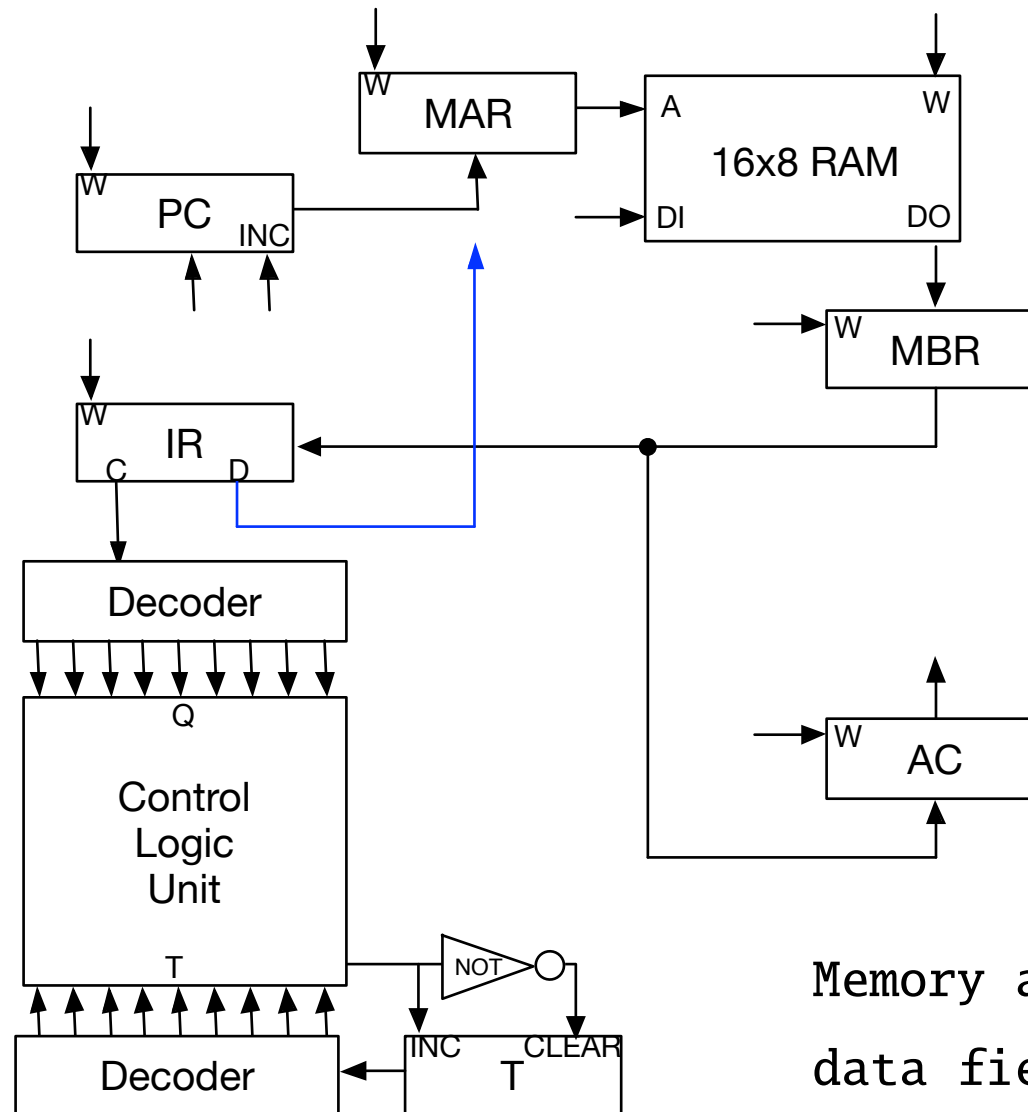
# AC ← MBR



Accumulator receives value from memory buffer (MBR)

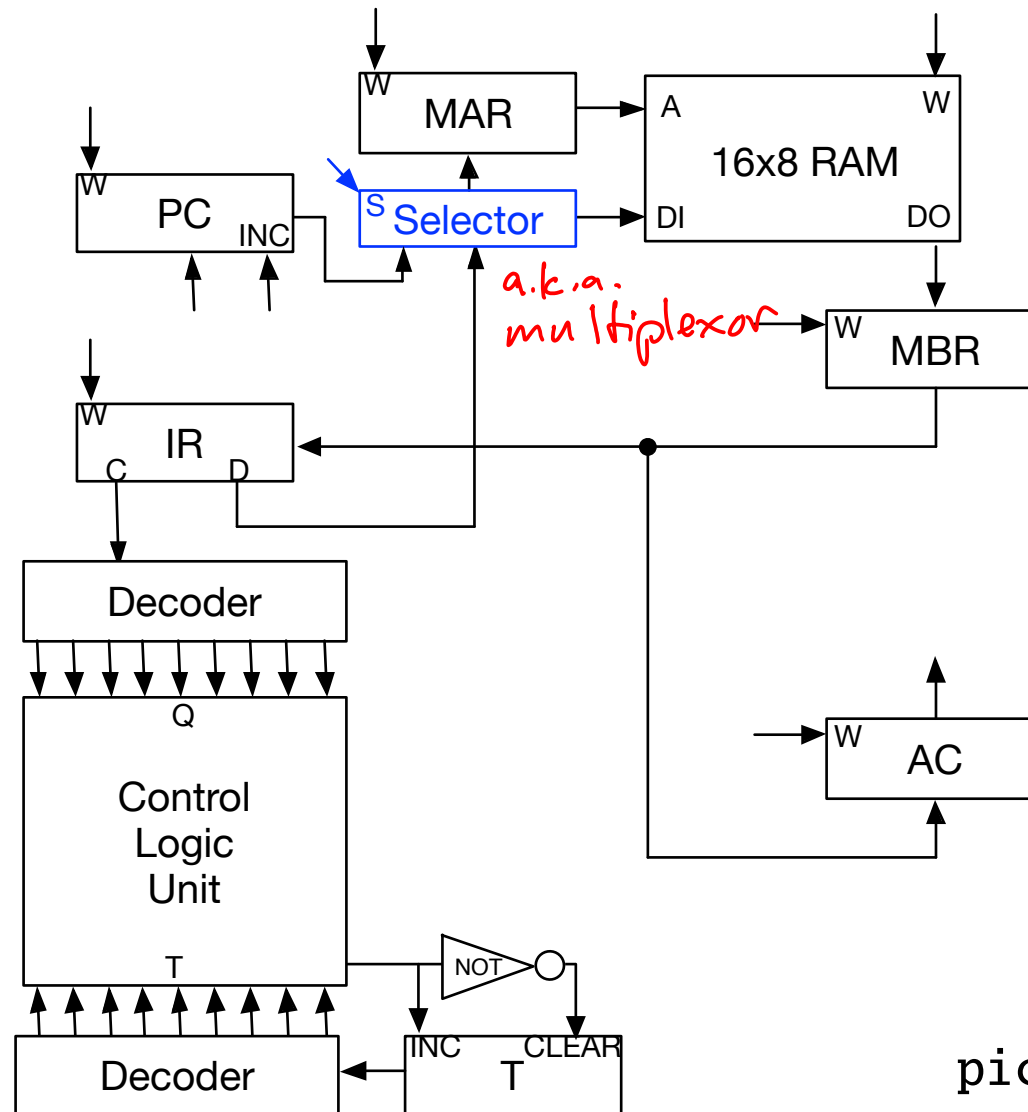


# MAR ← IR(D)



Memory address comes from data field of instruction

# MAR ← IR(D)



Selector  
picks between inputs

let's do this again

but focus on flags

# Micro Program

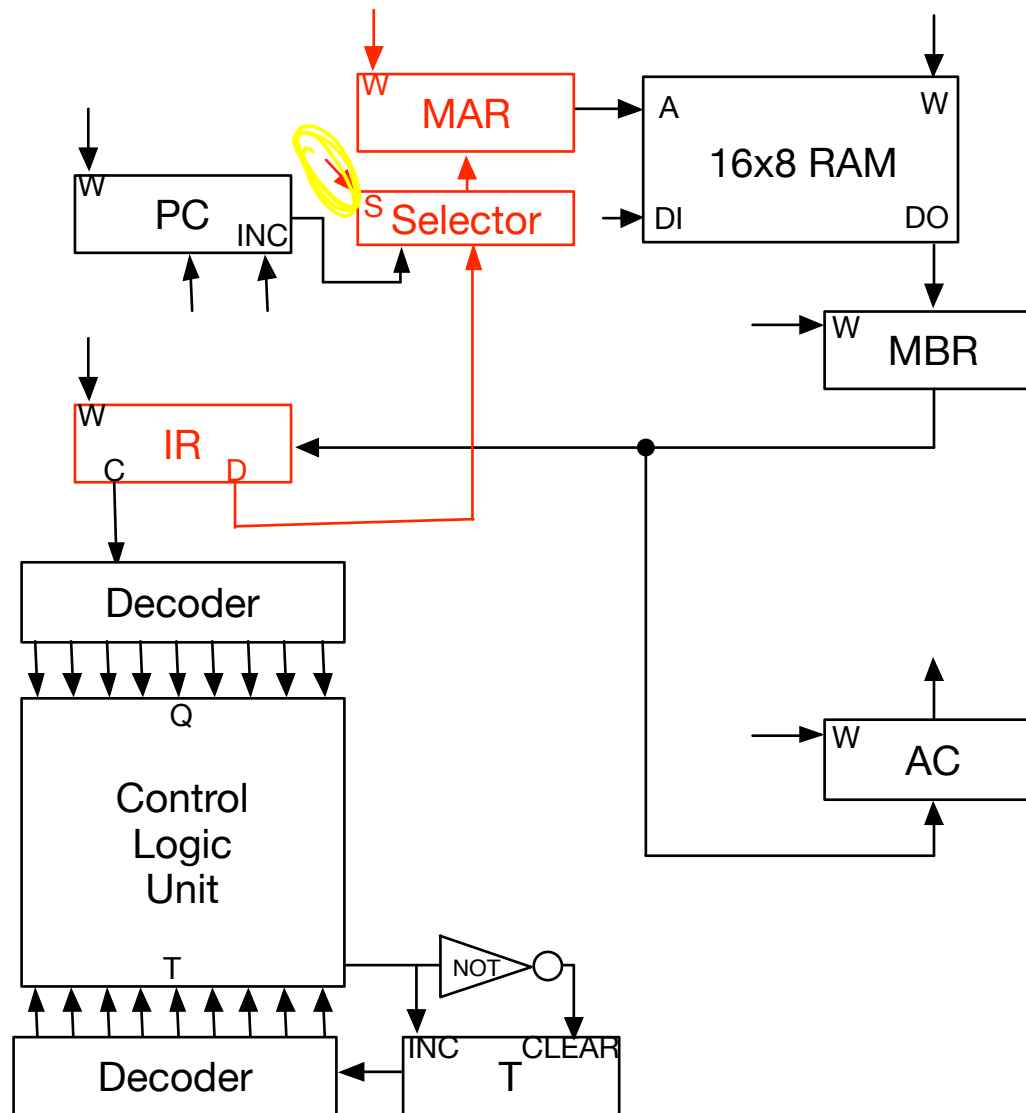


- Load into accumulator

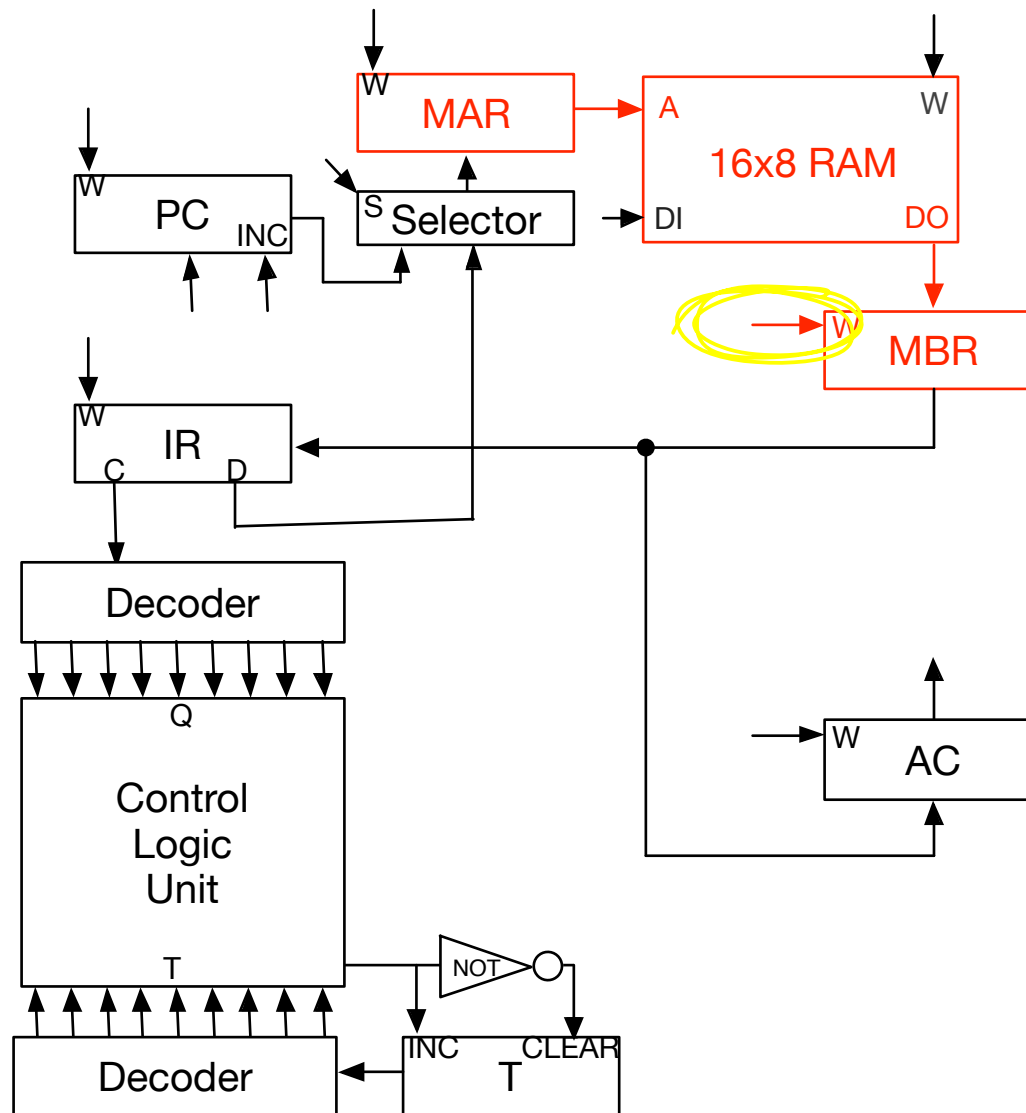
Op Code	Time	Command
q <sub>1</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>1</sub>	t <sub>4</sub>	MBR ← M
q <sub>1</sub>	t <sub>5</sub>	AC ← MBR

} Control Signals

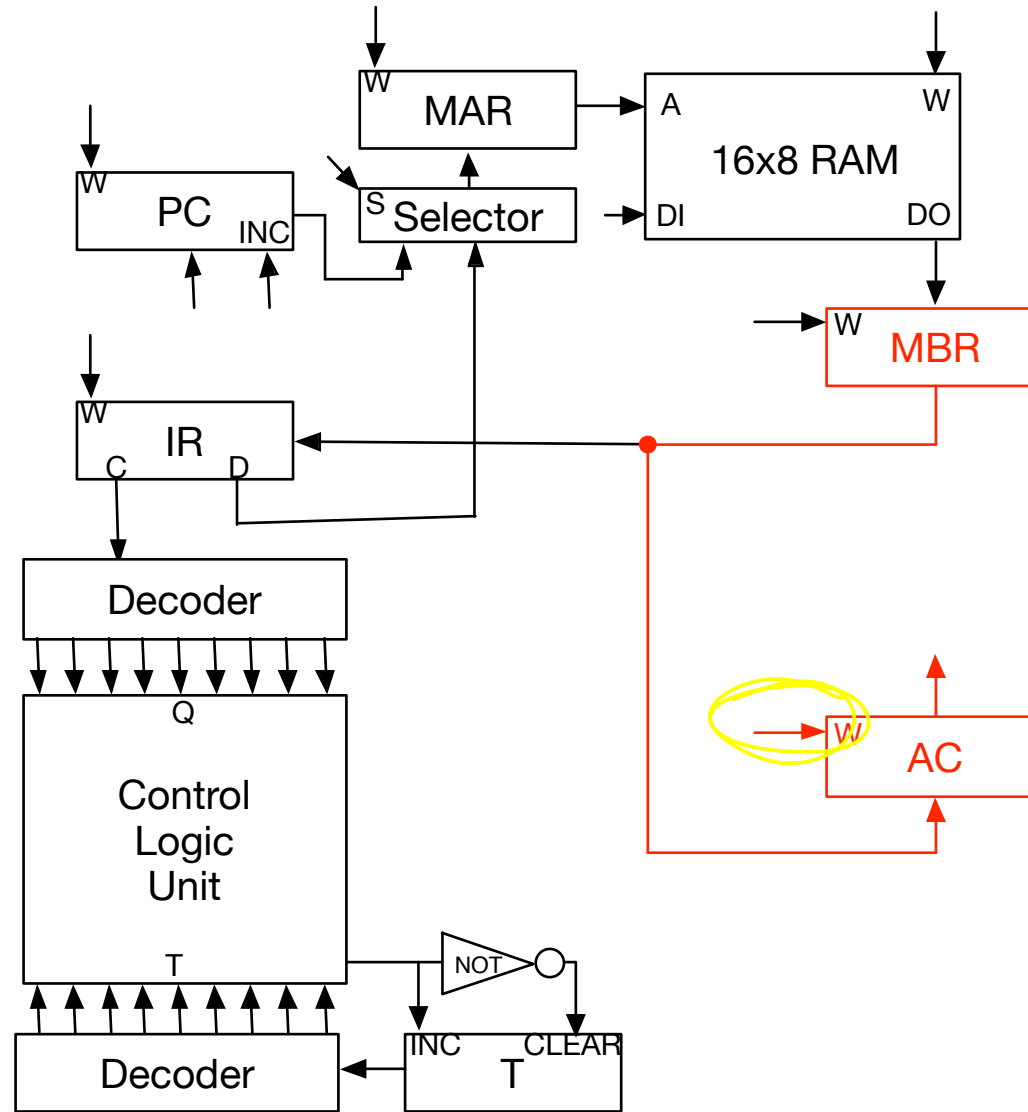
$q_1 \ t_3: \text{MAR} \leftarrow \text{IR}(D)$



$q_1 t_4$ : **MBR**  $\leftarrow$  **M**



$q_1 t_5: AC \leftarrow MBR$



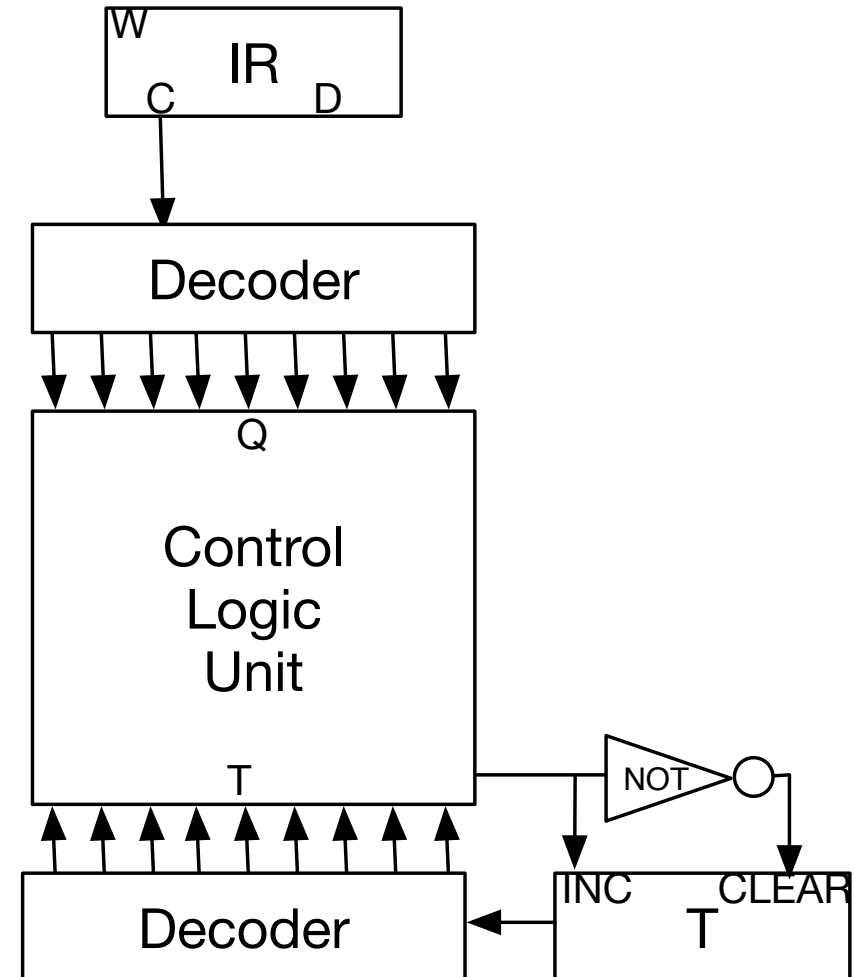


# control logic unit



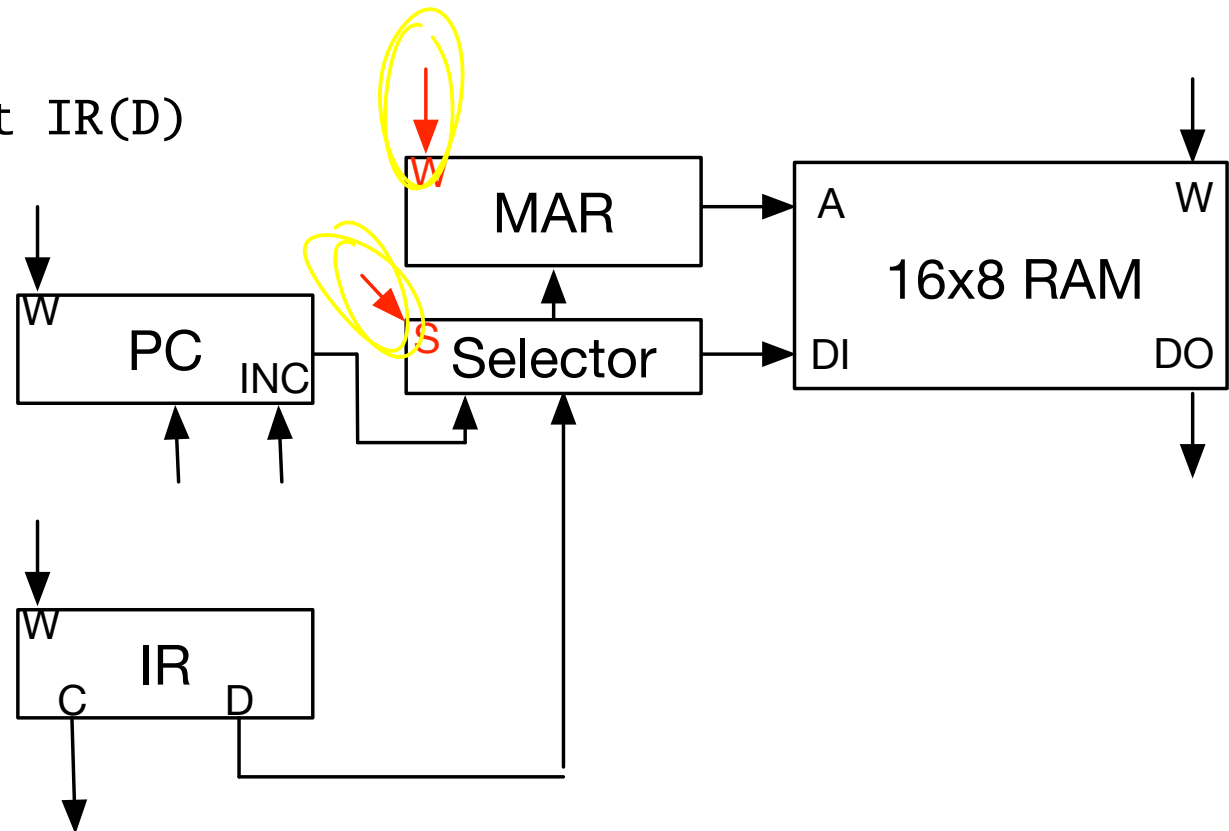
# Objective

- Given
  - Instruction op code  $Q$
  - Time step in micro program  $T$
- Output
  - signals to register transfer
  - signals to selectors

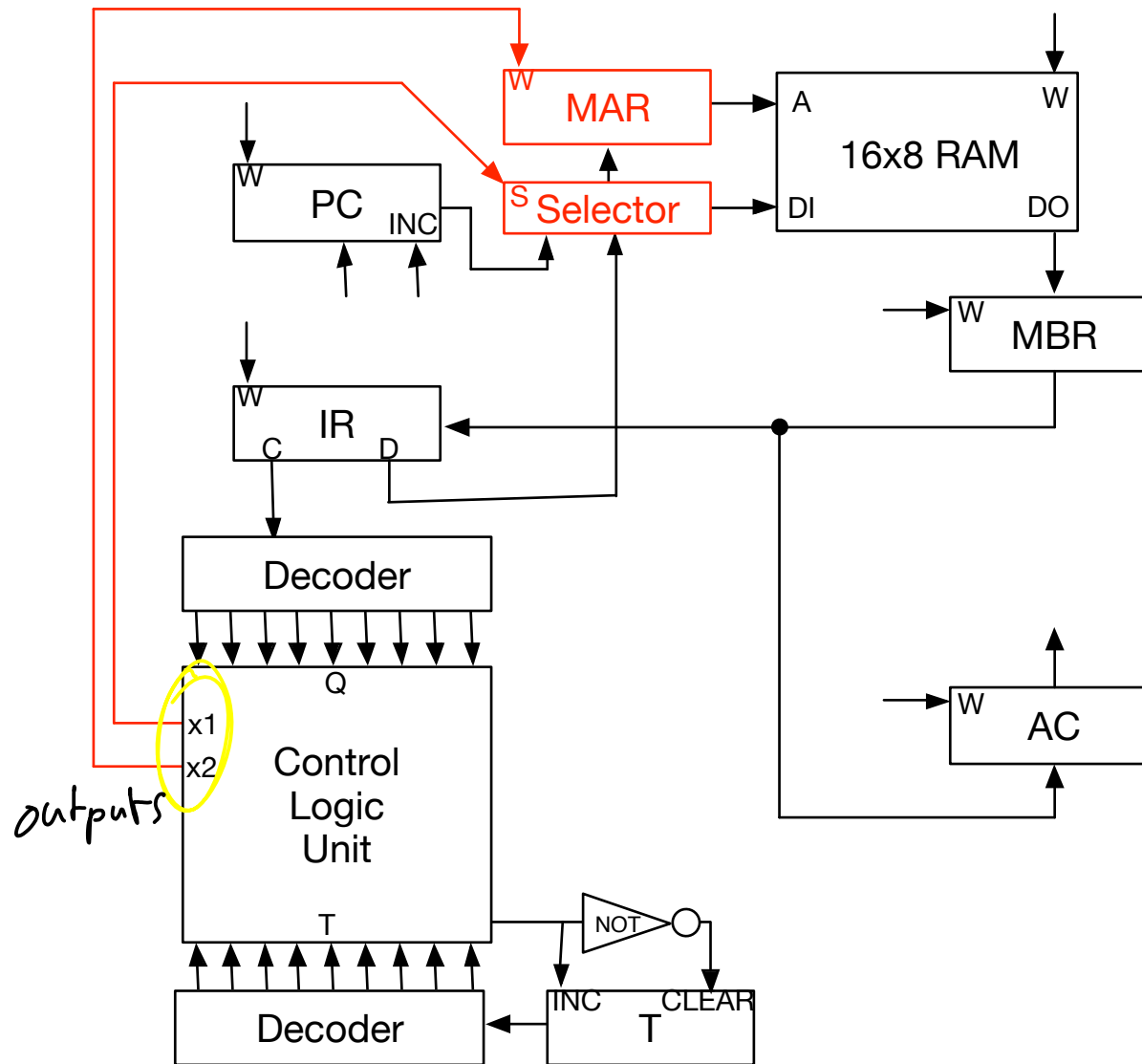


# Example

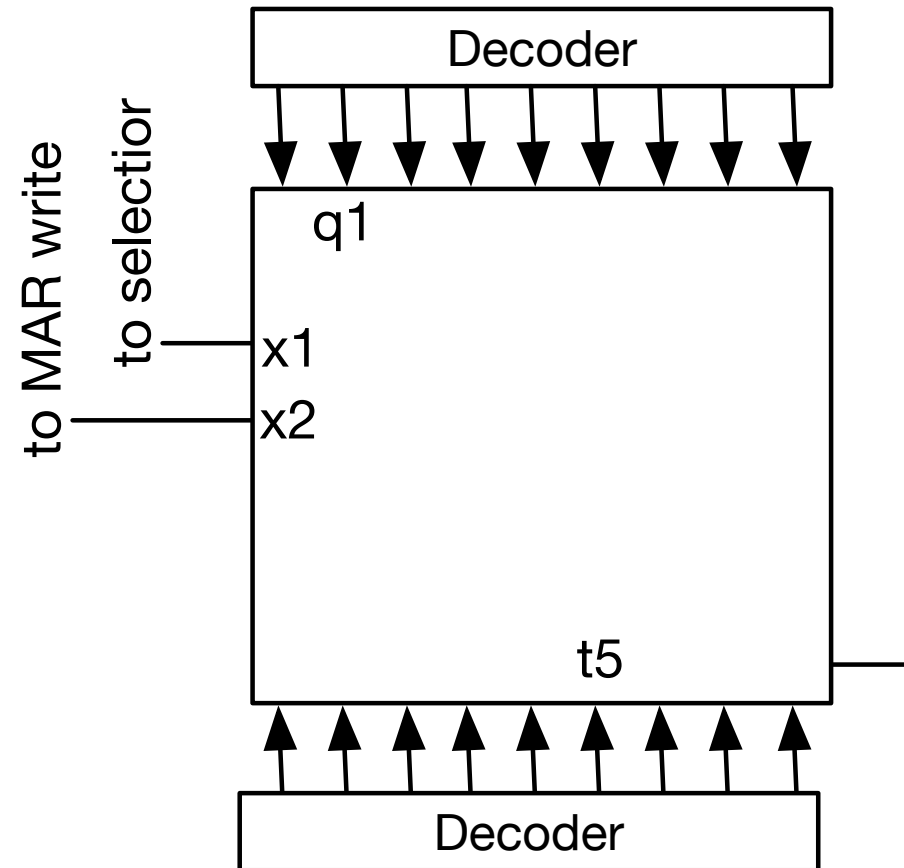
- Step in micro program:  $q_1 \ t_3 \text{ MAR} \leftarrow \text{IR}(D)$
- Needs to signal
  - MAR write flag set
  - MAR's selector to input IR(D)



# Add Wires to the Circuit

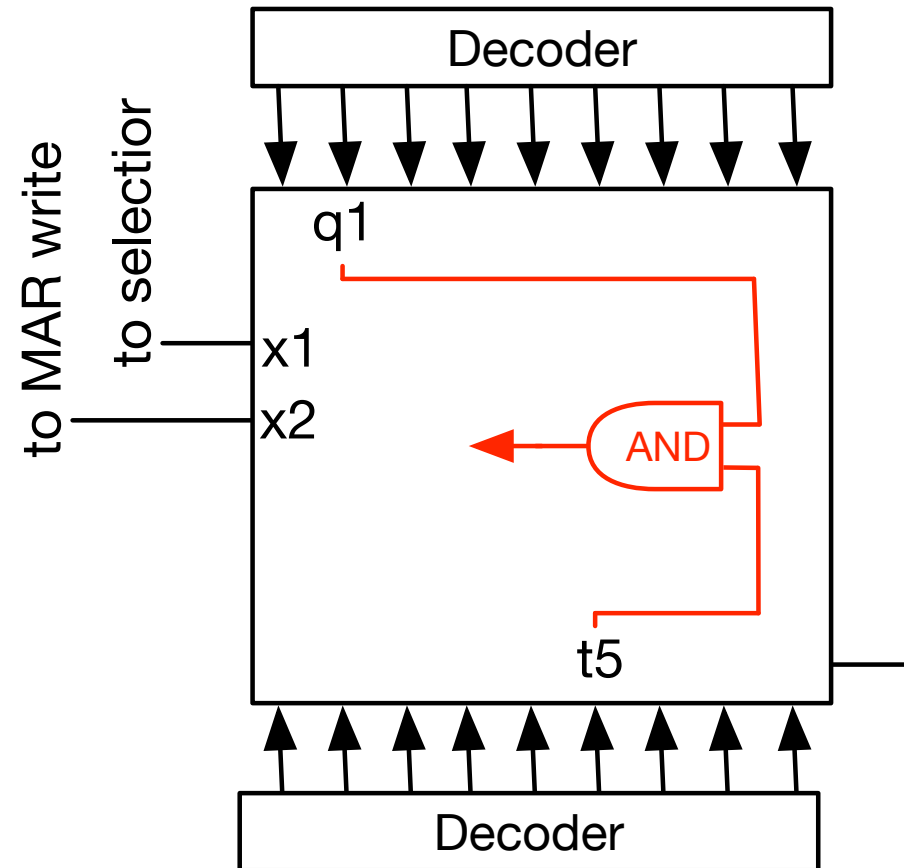


# Inside the Control Logic Unit



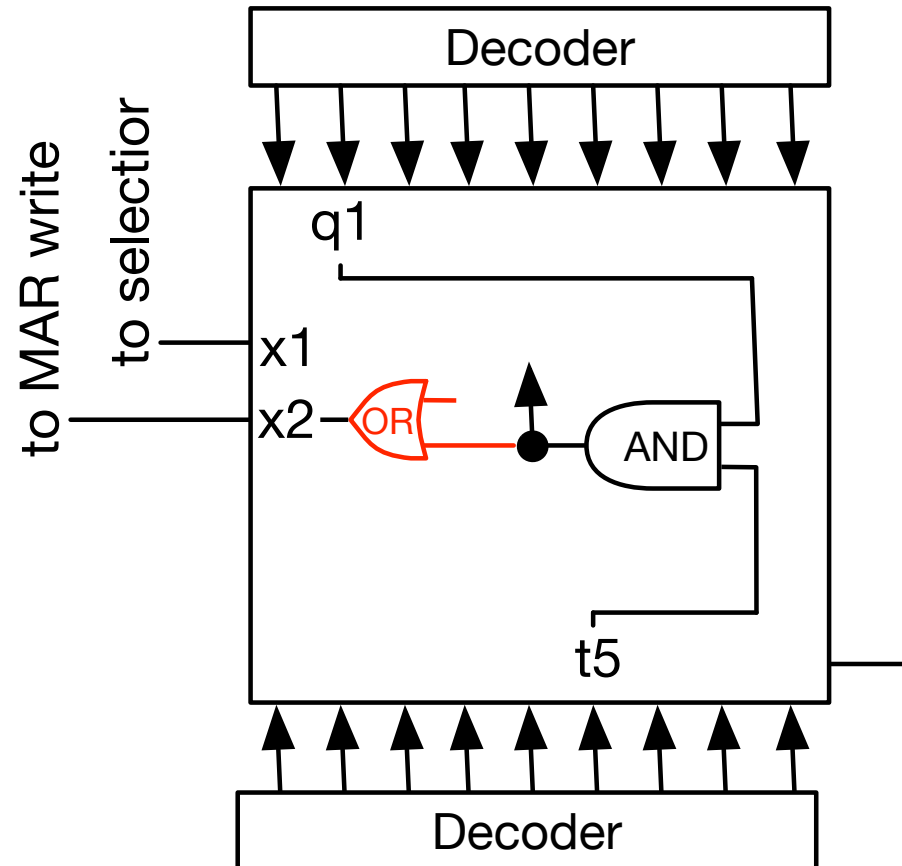
Micro instruction:  $q_1$  AND  $t_5$ :  $MAR \leftarrow IR(D)$

# Inside the Control Logic Unit



Micro instruction:  $q_1$  AND  $t_5$ :  $MAR \leftarrow IR(D)$

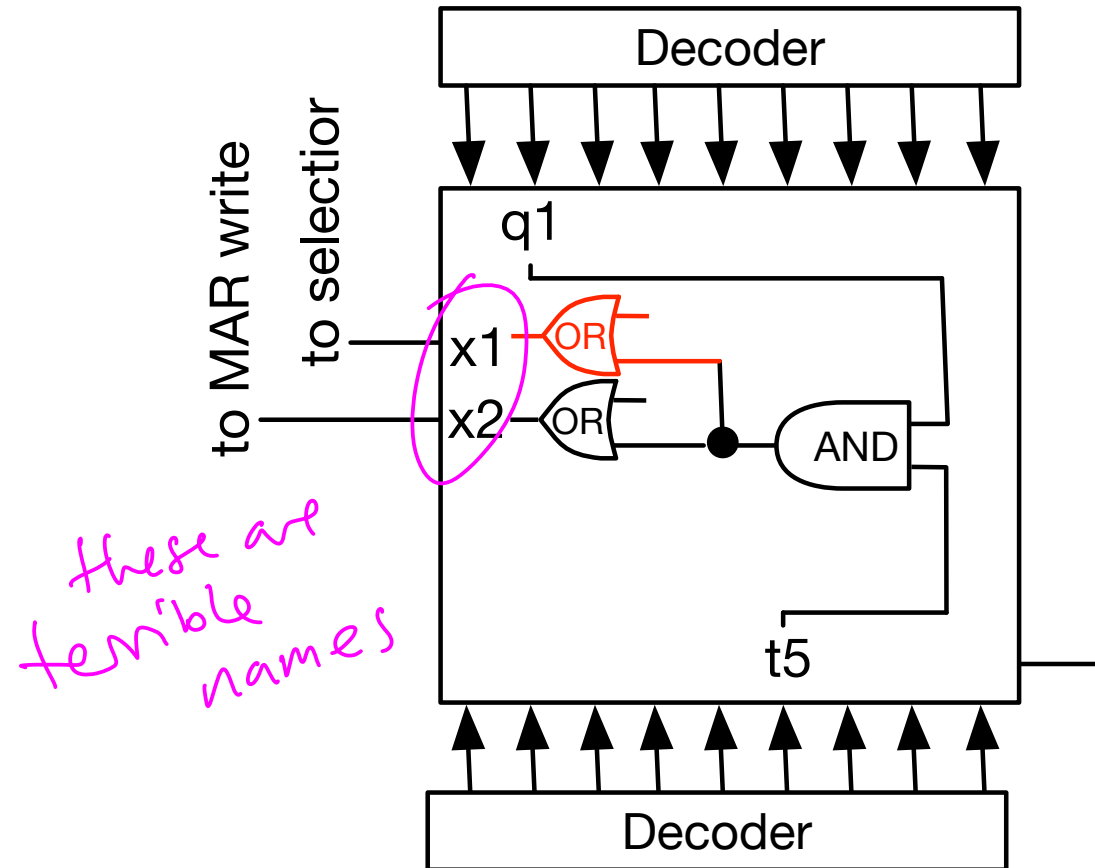
# Inside the Control Logic Unit



Micro instruction:  $q_1$  AND  $t_5$ :  $MAR \leftarrow IR(D)$

Set signal to MAR write flag

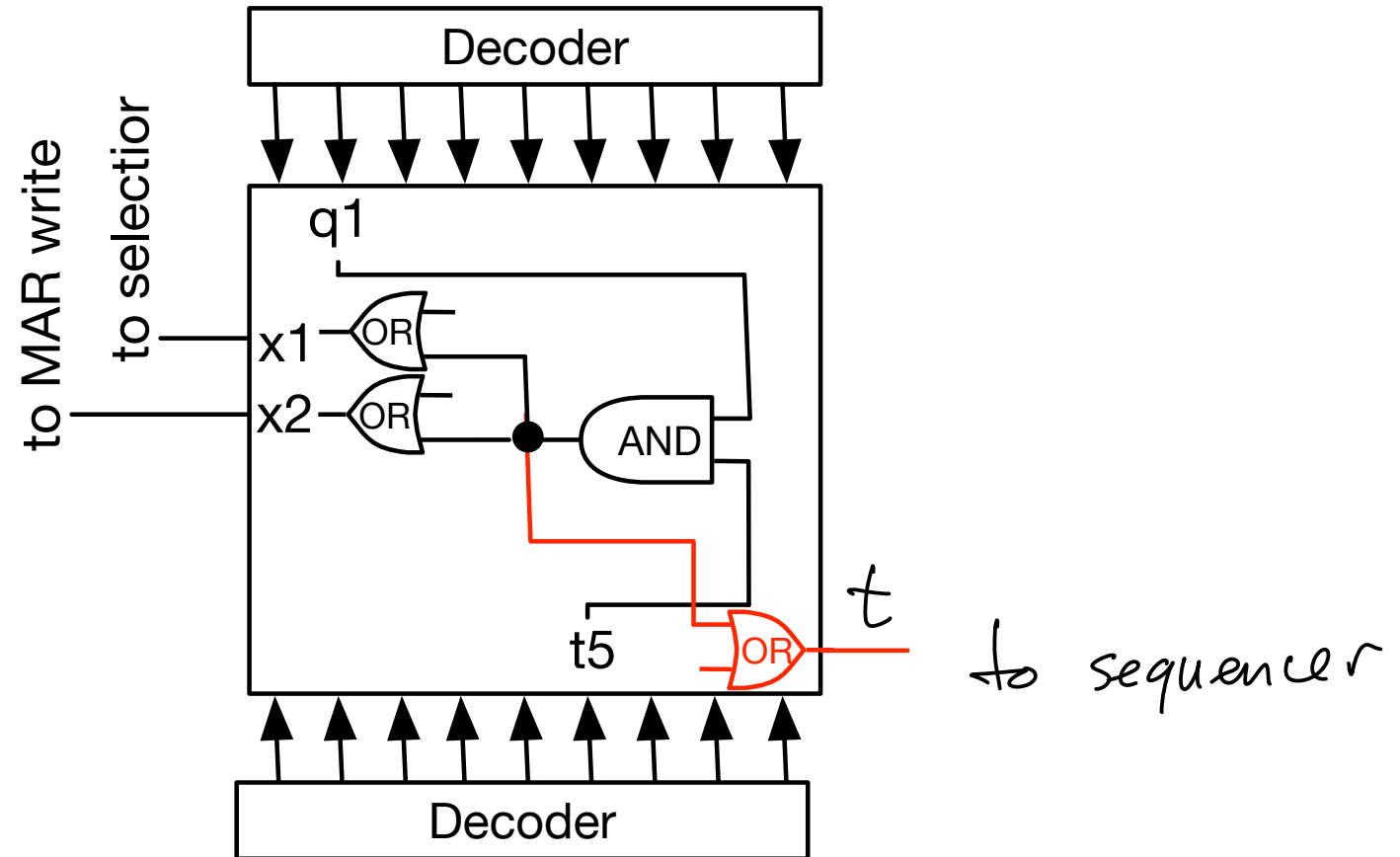
# Inside the Control Logic Unit



Micro instruction:  $q_1$  AND  $t_5$ :  $MAR \leftarrow IR(D)$

Set appropriate value to MAR selector

# Inside the Control Logic Unit



Micro instruction:  $q_1$  AND  $t_5$ :  $MAR \leftarrow IR(D)$

Increase micro program time step



# Inside the Control Logic Unit

Control logic is a large matrix

	t <sub>0</sub>	t <sub>1</sub>	t <sub>2</sub>	t <sub>3</sub>	t <sub>4</sub>	t <sub>5</sub>	t <sub>6</sub>	t <sub>7</sub>	t <sub>8</sub>
q <sub>0</sub>	*	*	*	*	*	*	*	*	*
q <sub>1</sub>	*	*	*	*	*	*	*	*	*
q <sub>2</sub>	*	*	*	*	*	*	*	*	*
q <sub>3</sub>	*	*	*	*	*	*	*	*	*
q <sub>4</sub>	*	*	*	*	*	*	*	*	*
q <sub>5</sub>	*	*	*	*	*	*	*	*	*
q <sub>6</sub>	*	*	*	*	*	*	*	*	*
q <sub>7</sub>	*	*	*	*	*	*	*	*	*
q <sub>8</sub>	*	*	*	*	*	*	*	*	*

# Inside the Control Logic Unit

Control logic is a large matrix

	$t_0$	$t_1$	$t_2$	$t_3$	$t_4$	$t_5$	$t_6$	$t_7$	$t_8$
$q_0$	*	*	*	*	*	*	*	*	*
$q_1$	*	*	*	*	*	*	*	*	*
$q_2$	*	*	*	*	*	*	*	*	*
$q_3$	*	*	*	*	*	*	*	*	*
$q_4$	*	*	*	*	*	*	*	*	*
$q_5$	*	*	*	*	*	*	*	*	*
$q_6$	*	*	*	*	*	*	*	*	*
$q_7$	*	*	*	*	*	*	*	*	*
$q_8$	*	*	*	*	*	*	*	*	*

# Inside the Control Logic Unit

Control logic is a large matrix

*Could use ROM!*

	$t_0$	$t_1$	$t_2$	$t_3$	$t_4$	$t_5$	$t_6$	$t_7$	$t_8$
$q_0$	*	*	*	*	*	*	*	*	*
$q_1$	*	*	*	*	*	$x_1x_2t$	*	*	*
$q_2$	*	*	*	*	*	*	*	*	*
$q_3$	*	*	*	*	*	*	*	*	*
$q_4$	*	*	*	*	*	*	*	*	*
$q_5$	*	*	*	*	*	*	*	*	*
$q_6$	*	*	*	*	*	*	*	*	*
$q_7$	*	*	*	*	*	*	*	*	*
$q_8$	*	*	*	*	*	*	*	*	*



# ldi

# LDI: Load Indirectly

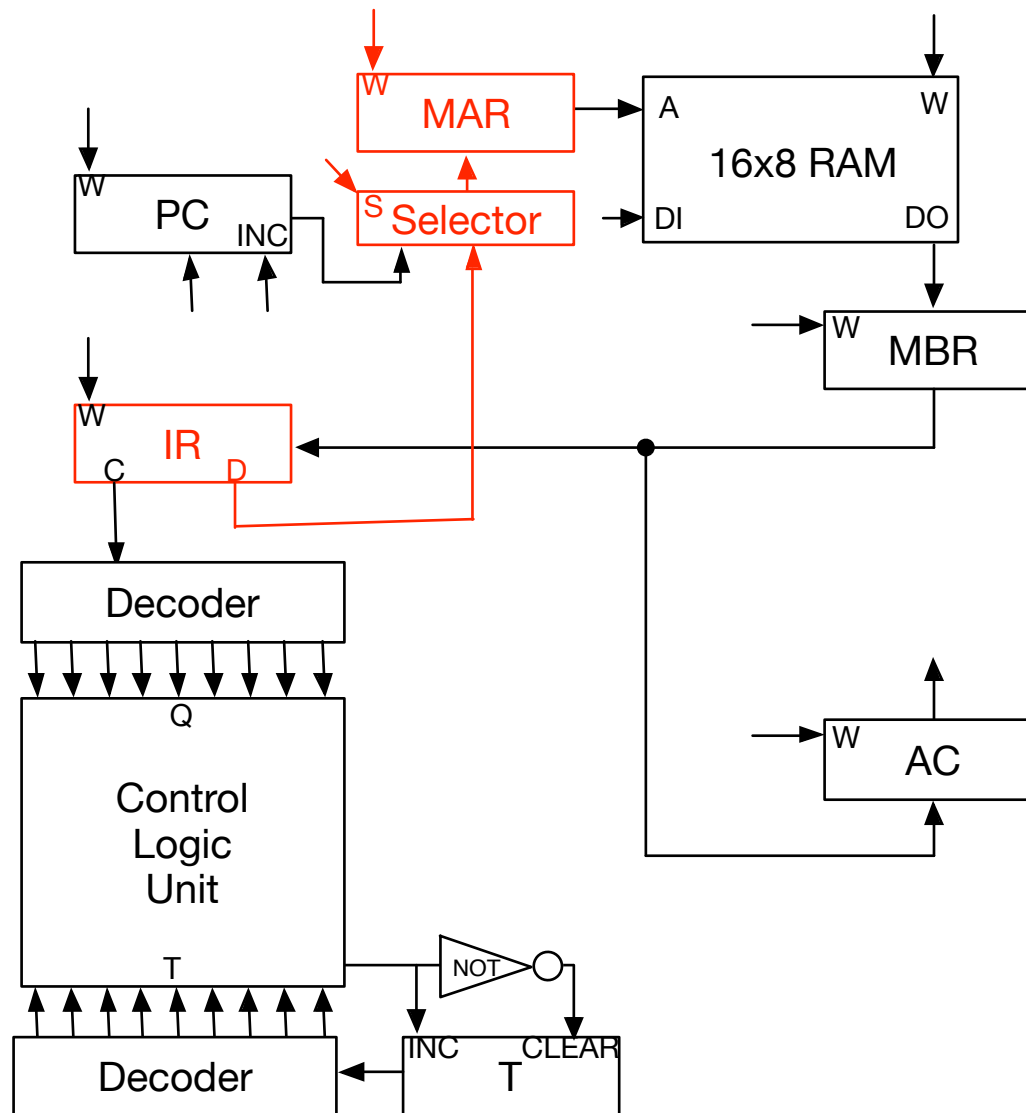
- Specified memory address contains address for value
- Basically a pointer operation
- Steps
  - load value of specified memory address
  - use that value as a memory address (second lookup)
  - store value from second lookup into accumulator

# Micro Program for LDI

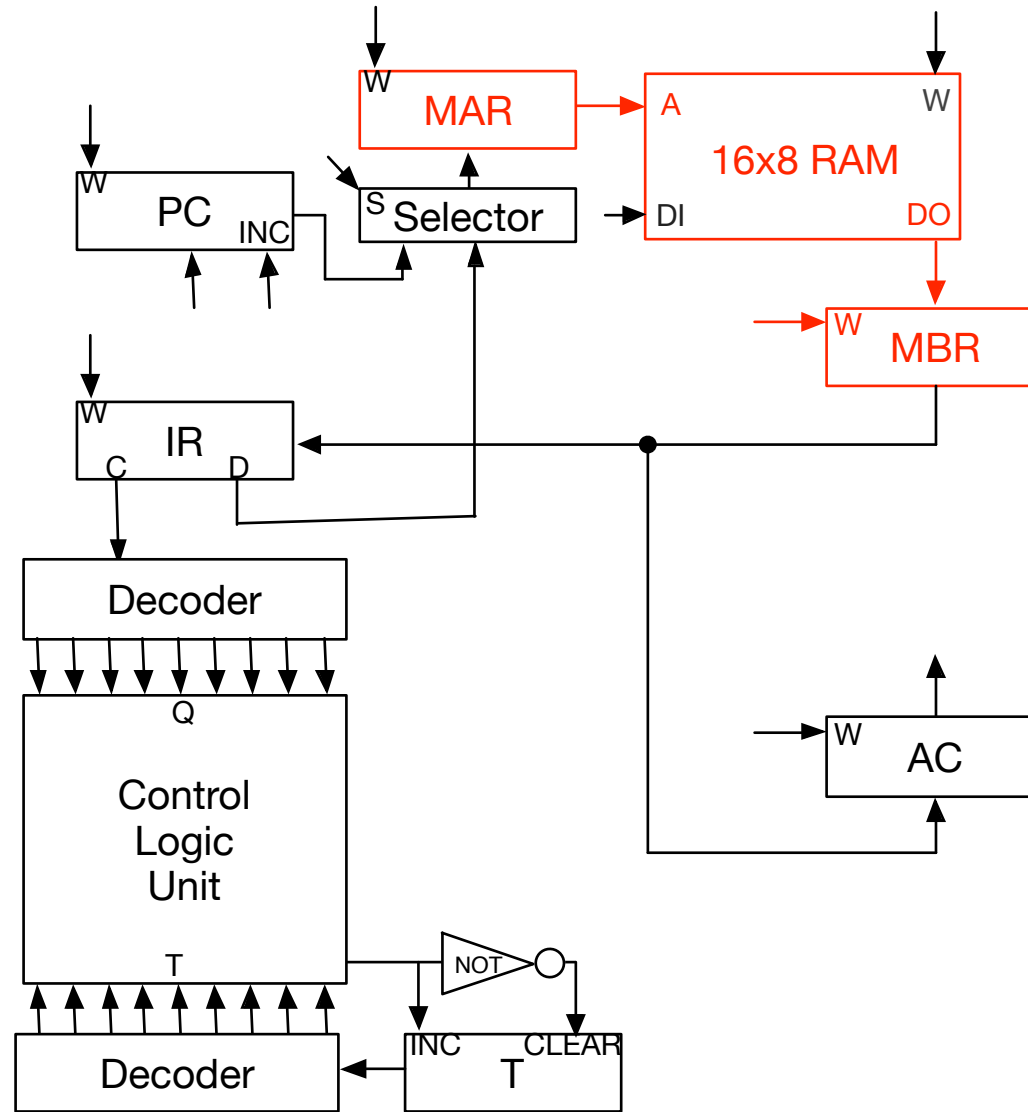
- Load indirectly into accumulator

Op Code	Time	Command
q <sub>2</sub>	t <sub>3</sub>	MAR ← IR(D) *
q <sub>2</sub>	t <sub>4</sub>	MBR ← M
q <sub>2</sub>	t <sub>5</sub>	MAR ← MBR * (low 4 bits)
q <sub>2</sub>	t <sub>6</sub>	MBR ← M
q <sub>2</sub>	t <sub>7</sub>	AC ← MBR

$q_2 \ t_3: \text{MAR} \leftarrow \text{IR}(D)$

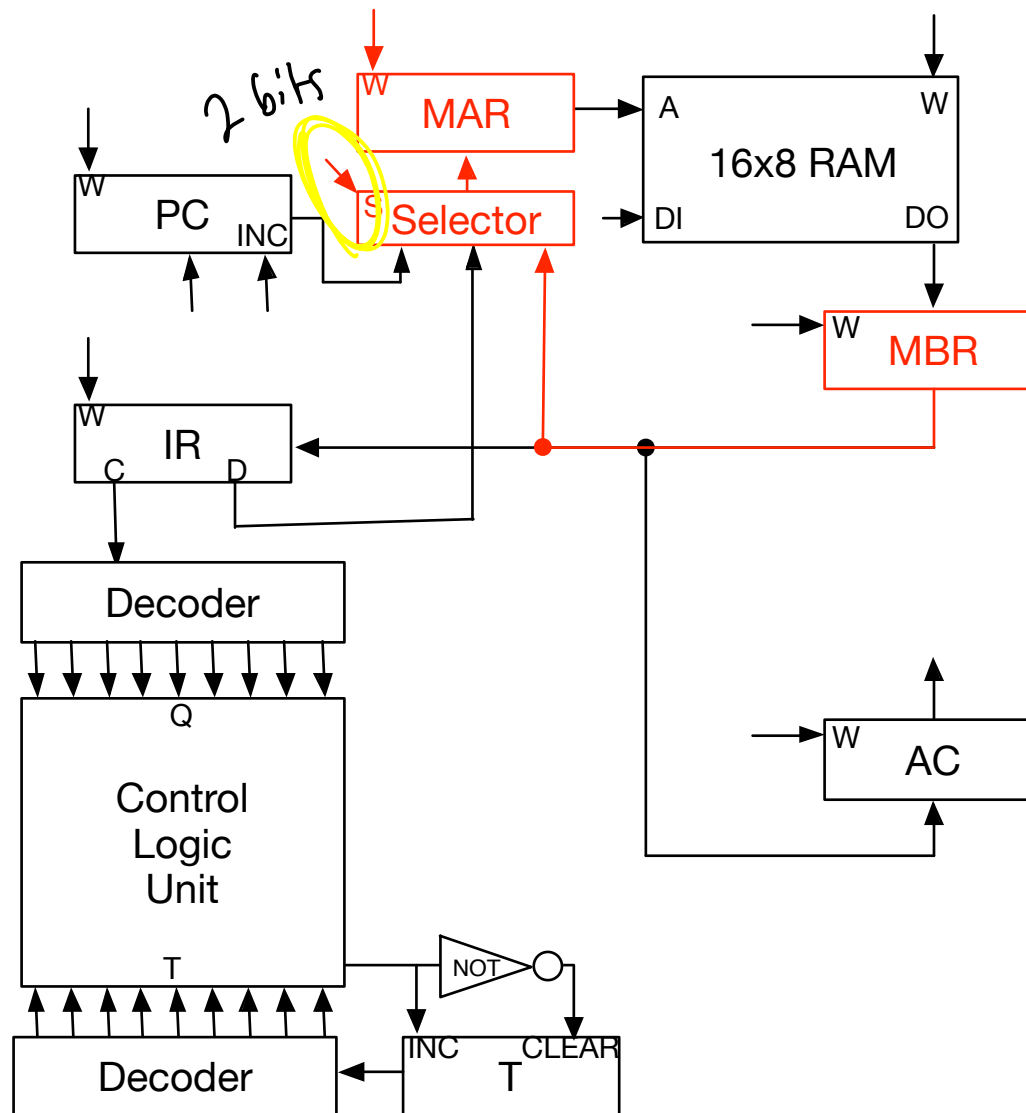


$q_2 \ t_4$ : **MBR**  $\leftarrow$  **M**

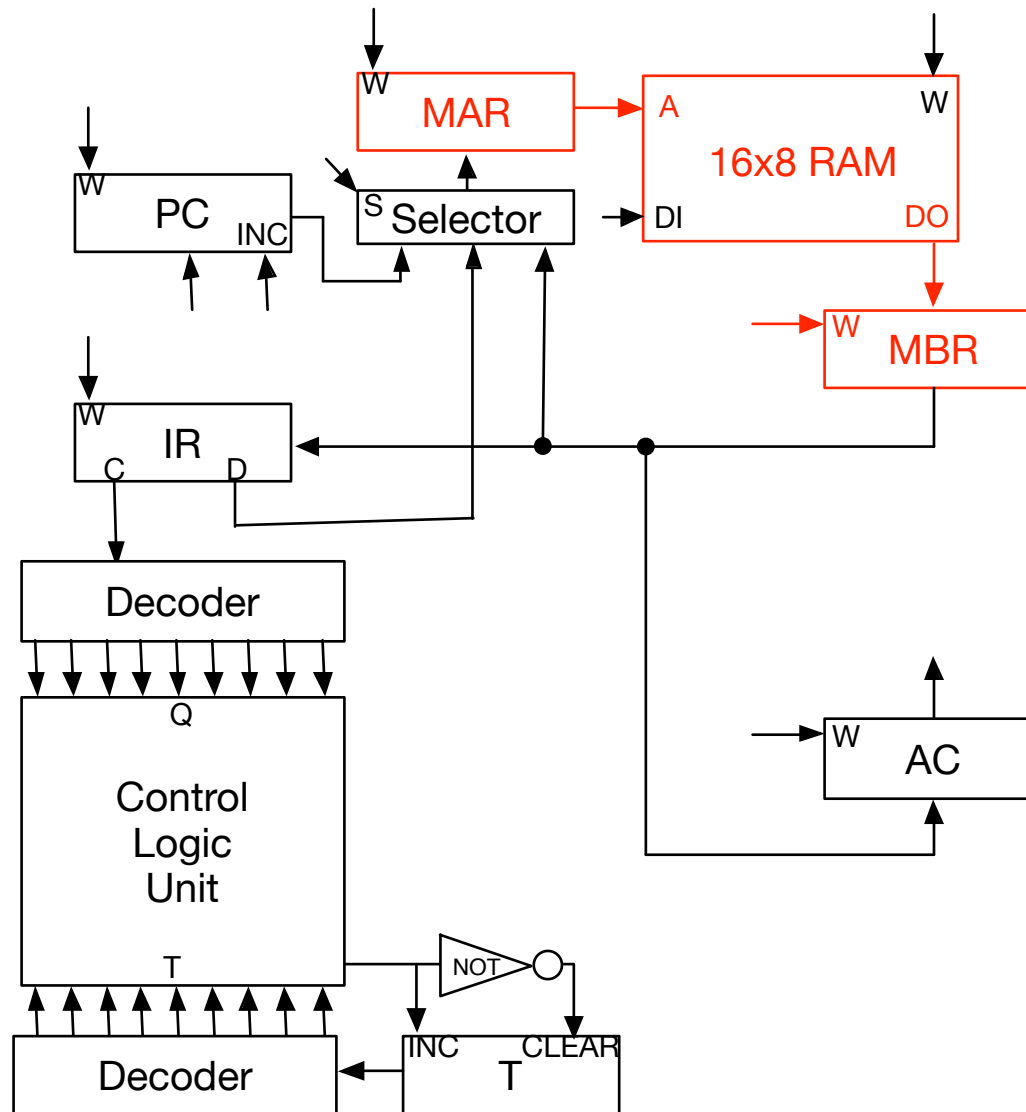




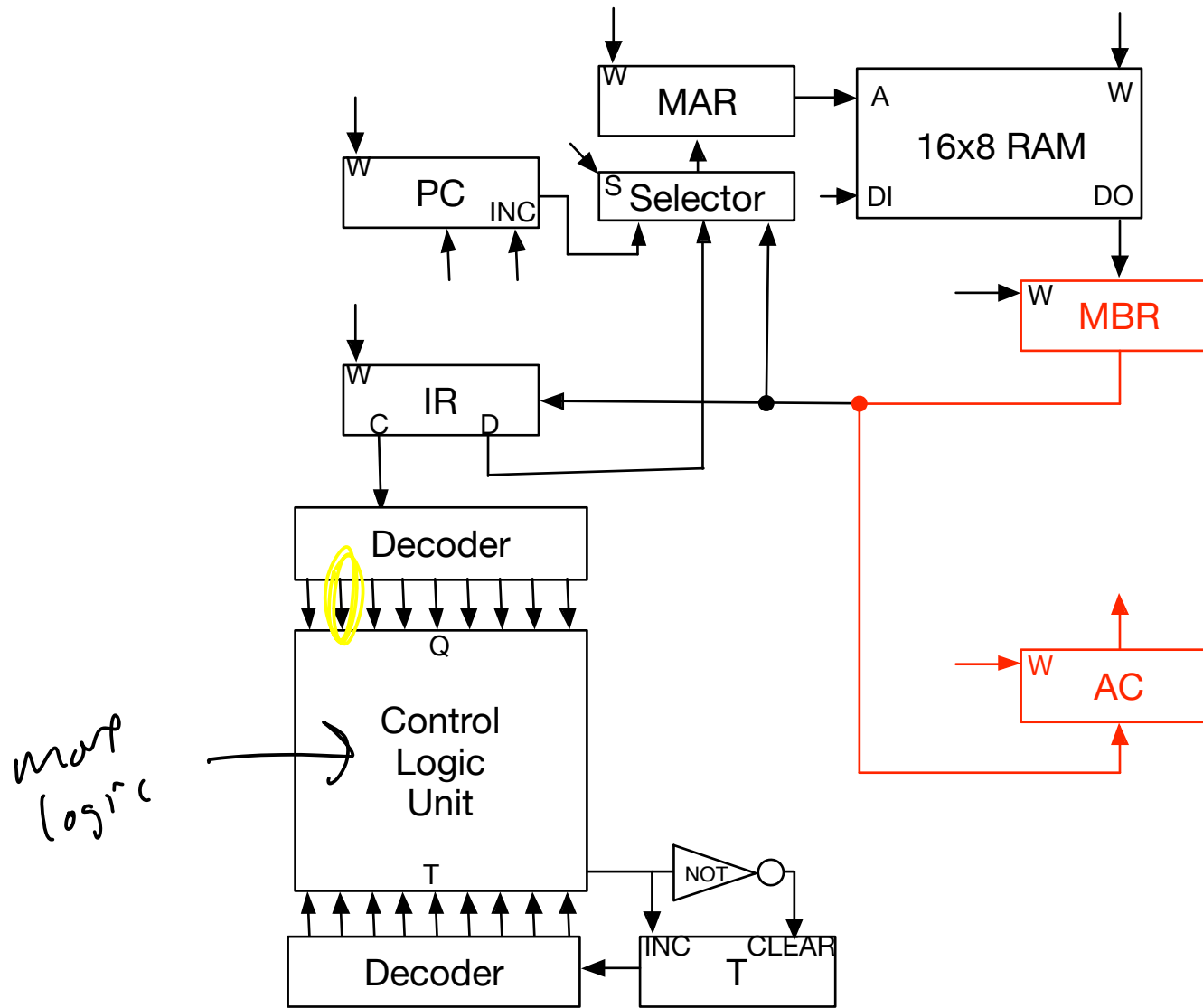
$q_2 t_5$ : **MAR**  $\leftarrow$  **MBR**



q<sub>2</sub> t<sub>6</sub>: MBR ← M



q<sub>2</sub> t<sub>7</sub>: AC ← MBR





sta

# STA: Store Value from Accumulator



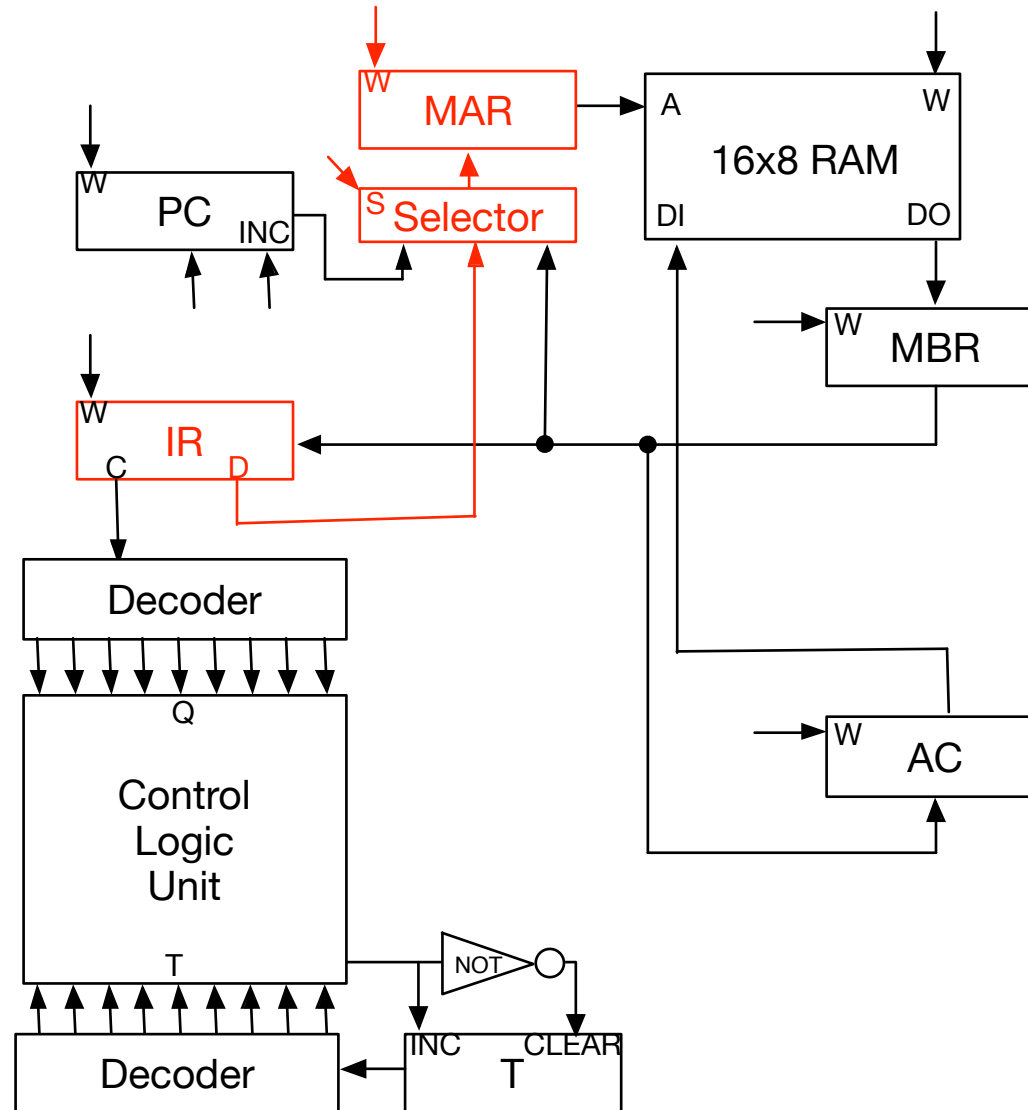
- We now need to write to memory
- Address to be written with comes from instruction
- Value needs to be transferred from accumulator

# Micro Program for STA

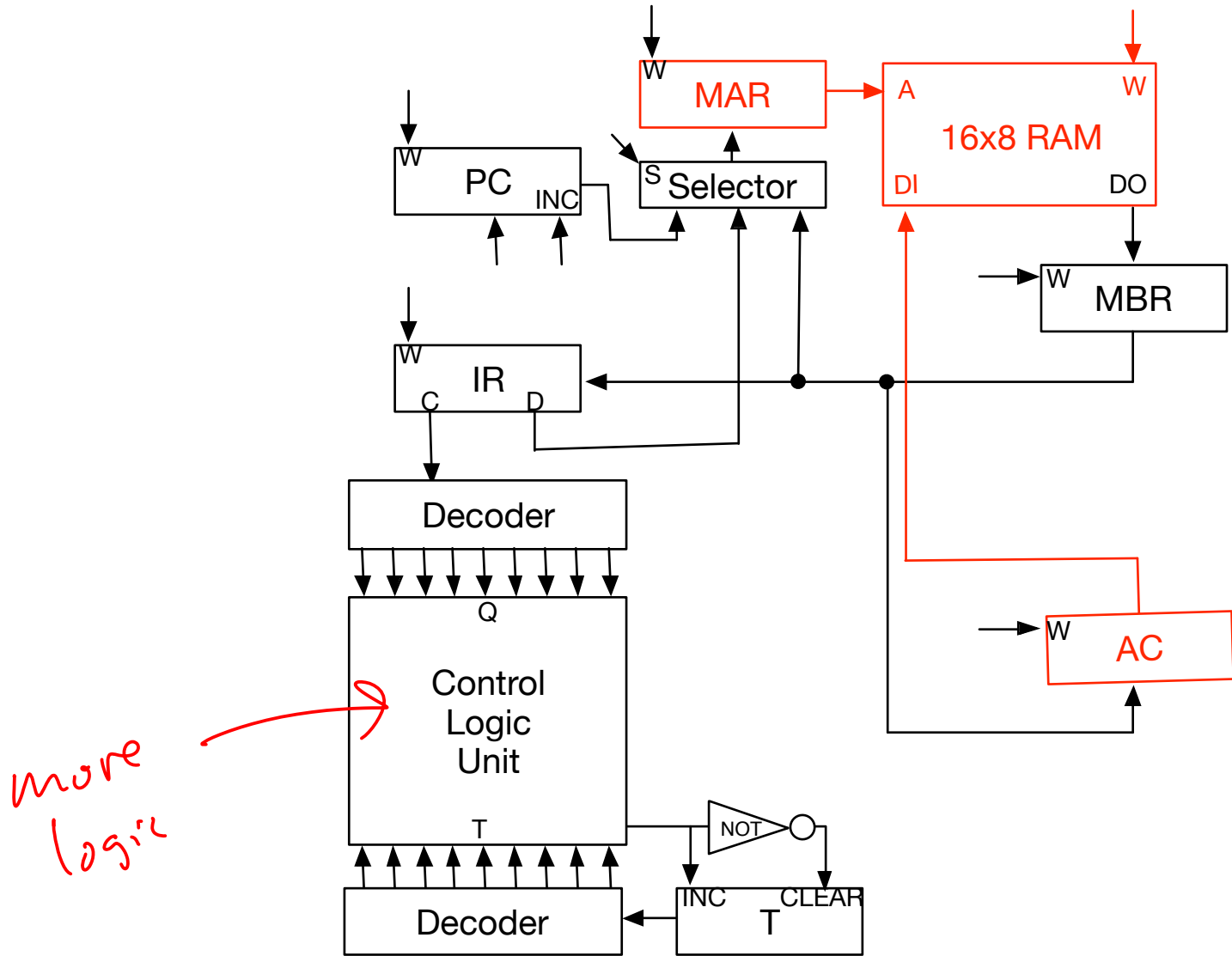
- Store value from accumulator

Op Code	Time	Command
q <sub>3</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>3</sub>	t <sub>4</sub>	M ← AC *

$q_3 \ t_3: \text{MAR} \leftarrow \text{IR}(D)$



$q_3 \ t_4: \ M \leftarrow AC$







`sti`

# STI: Store Value Indirectly



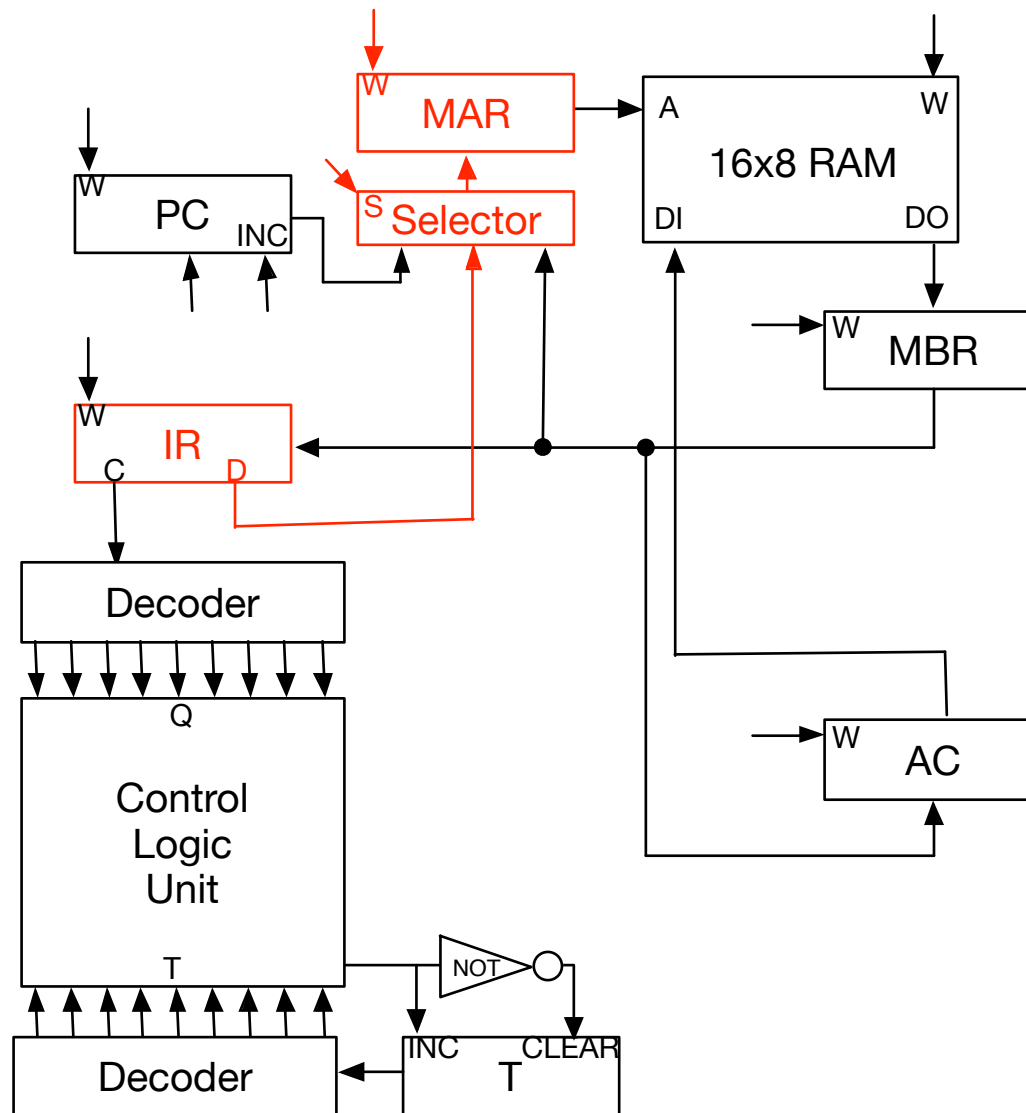
- Specified memory address contains address for value
- Steps
  - load value of specified memory address
  - use that value as a memory address (second lookup)
  - store value from accumulator to that address

# Micro Program for STI

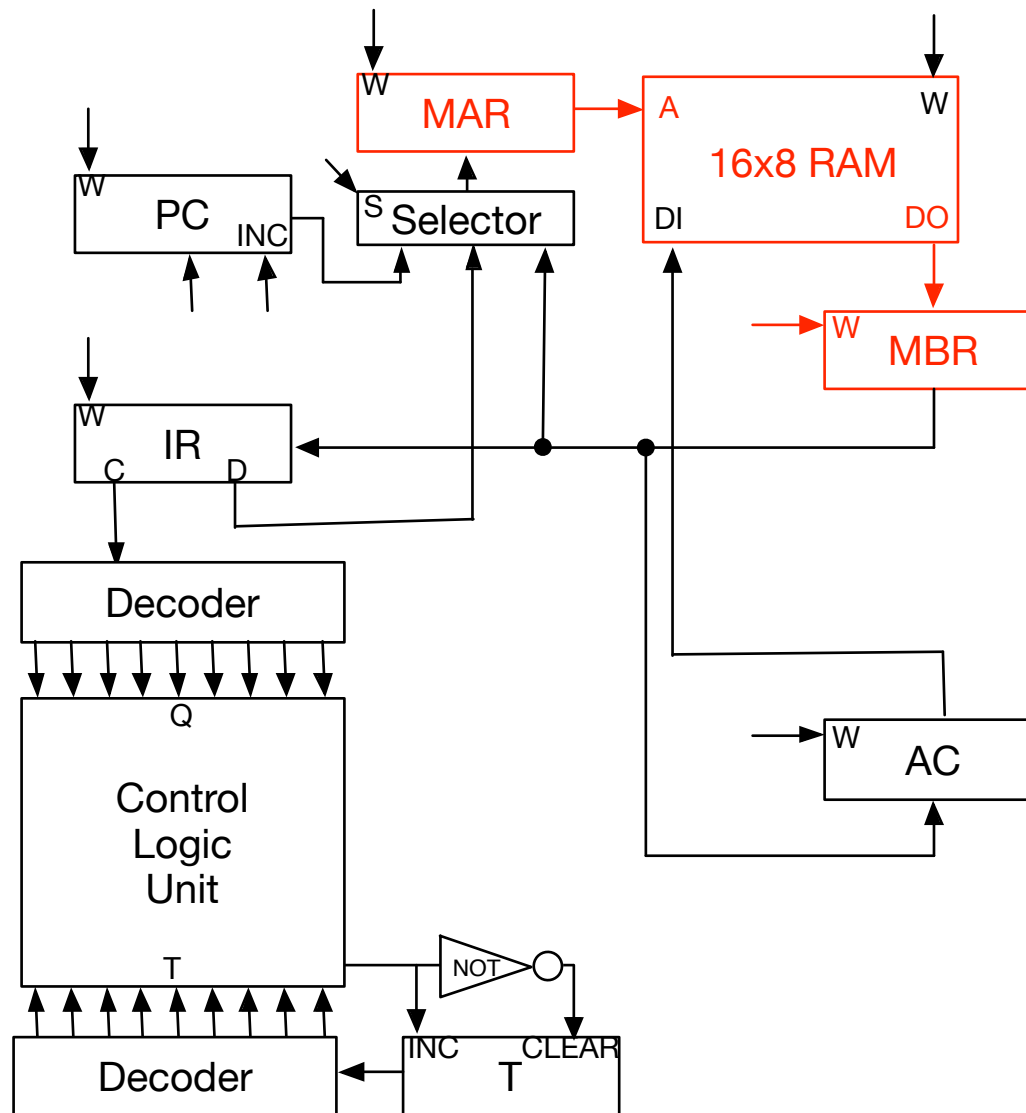
- Store indirectly into accumulator

Op Code	Time	Command
q <sub>4</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>4</sub>	t <sub>4</sub>	MBR ← M
q <sub>4</sub>	t <sub>3</sub>	MAR ← MBR *
q <sub>4</sub>	t <sub>4</sub>	M ← AC

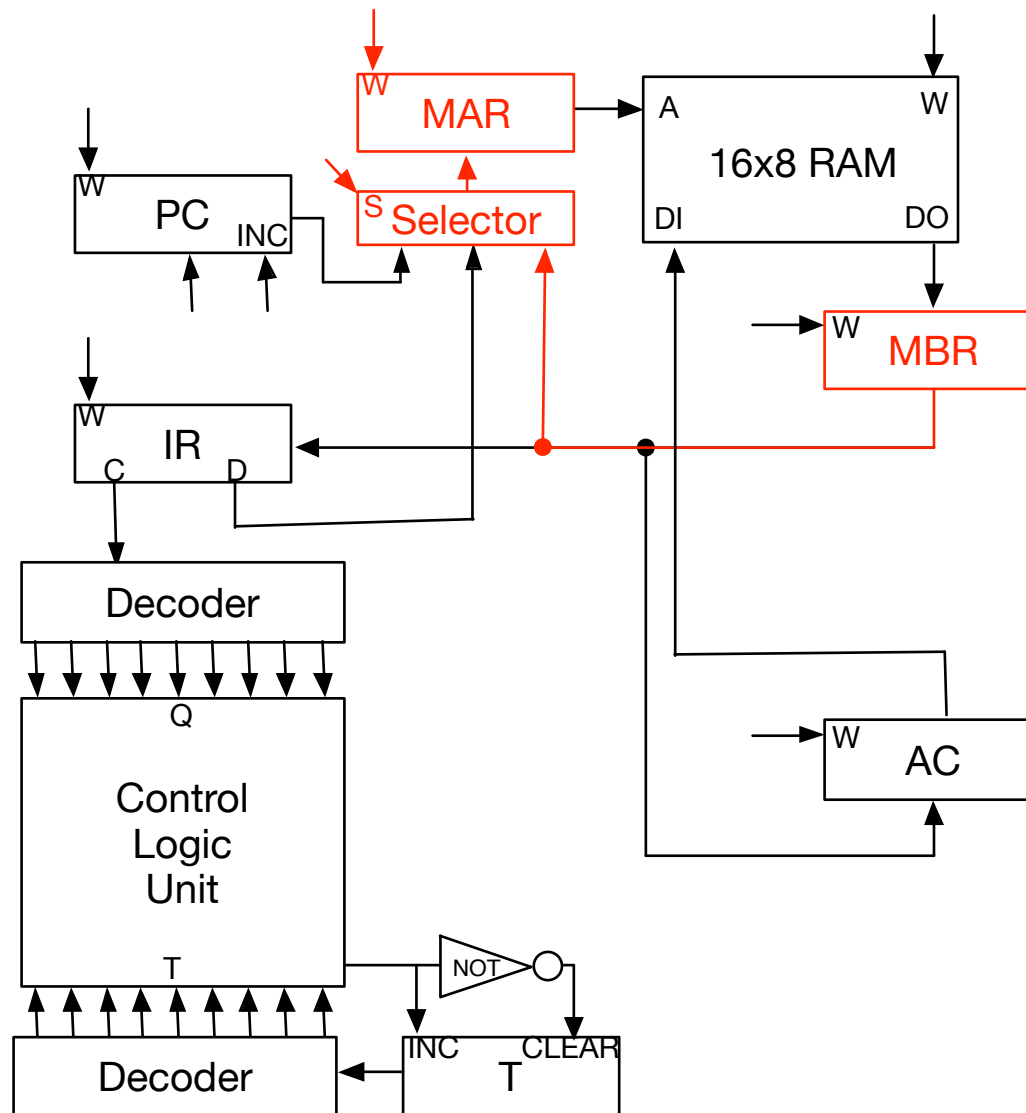
$q_4 \ t_3: \text{MAR} \leftarrow \text{IR}(D)$



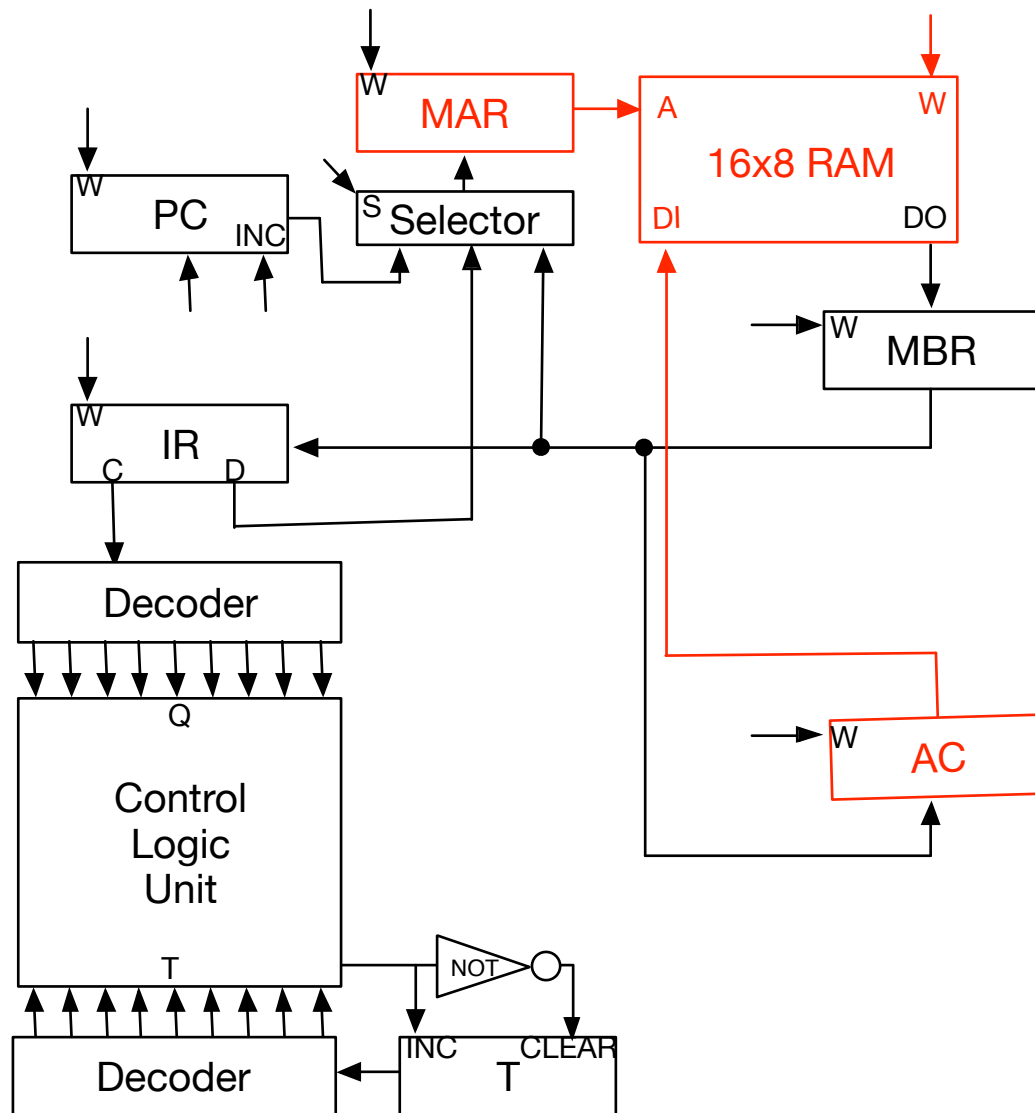
$q_4 \ t_4: \text{ MBR} \leftarrow \text{M}$



$q_4 \ t_5: \text{MAR} \leftarrow \text{MBR}$



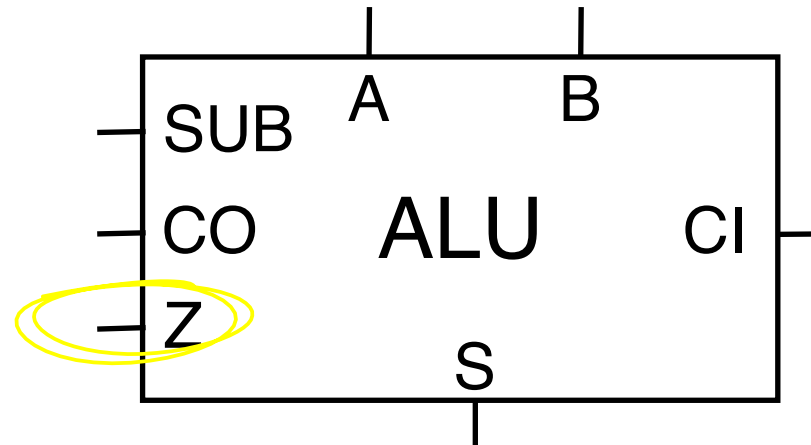
$q_4 \ t_6: \ M \leftarrow AC$



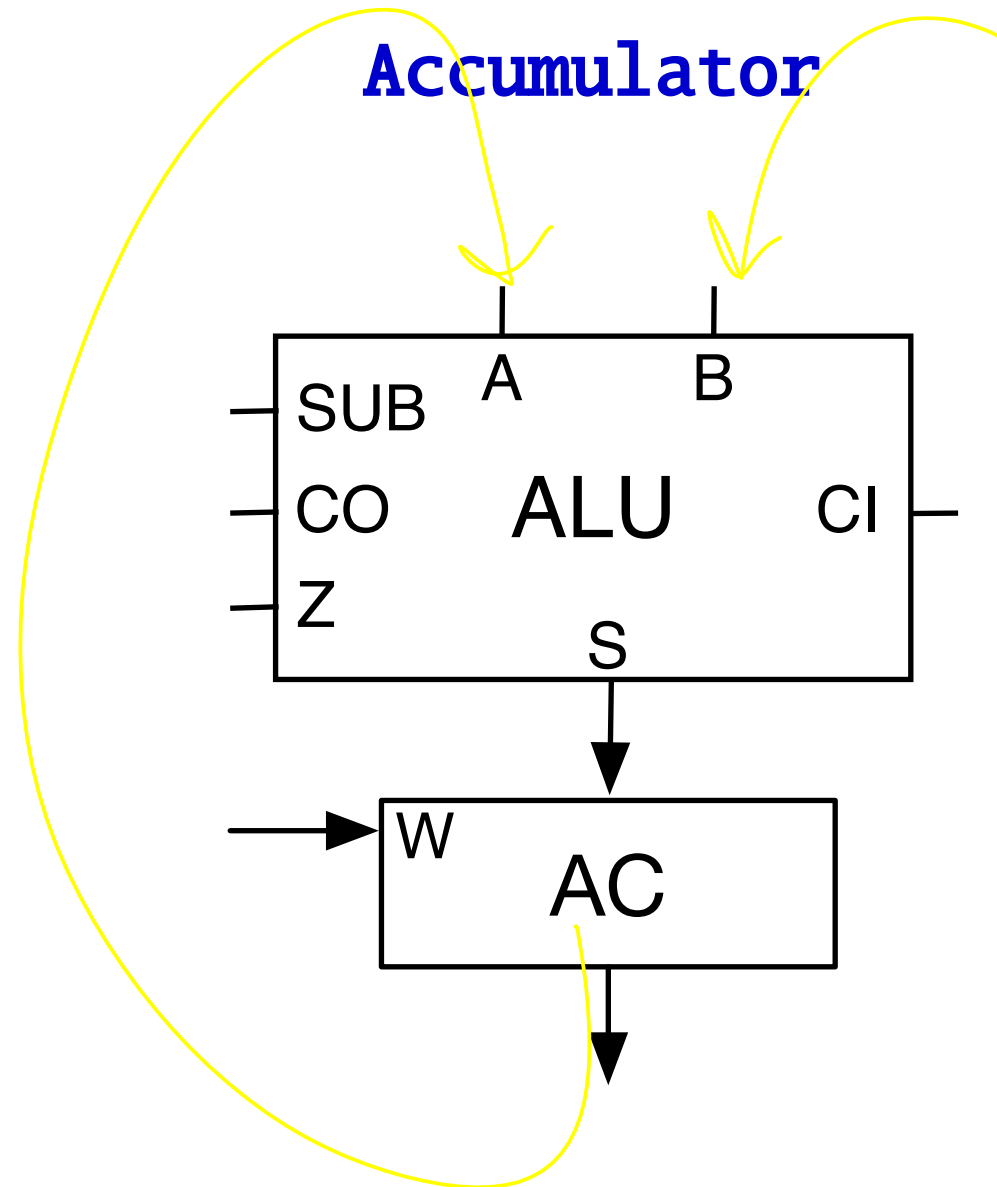
# arithmetic logic unit



# Arithmetic Logic Unit

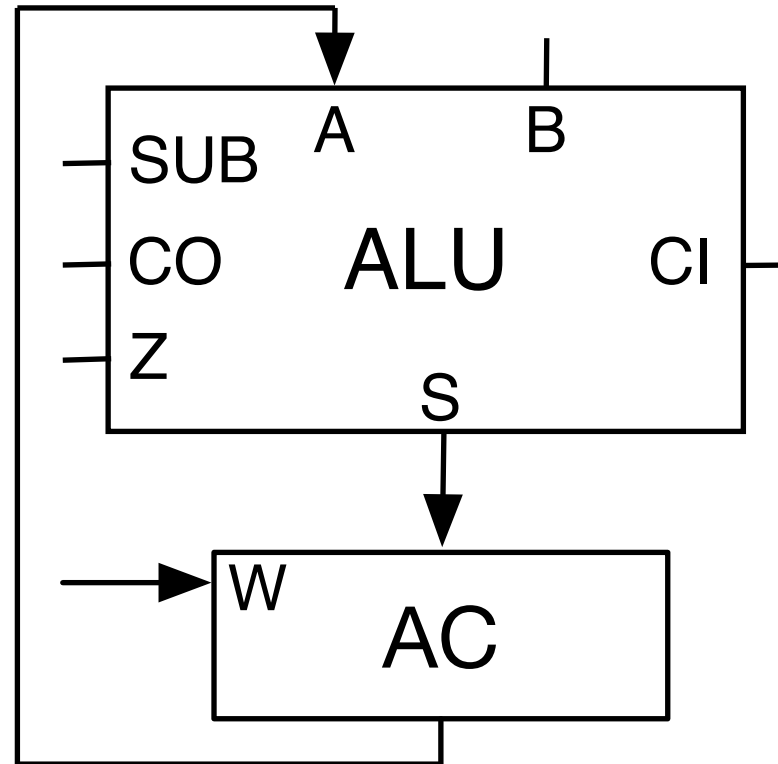


- Adds two numbers:  $S=A+B$
- With subtraction flag:  $S=A-B$
- Overflow handling with carry in (CI) and carry out (CO)
- Zero flag: set if result of operation is 0



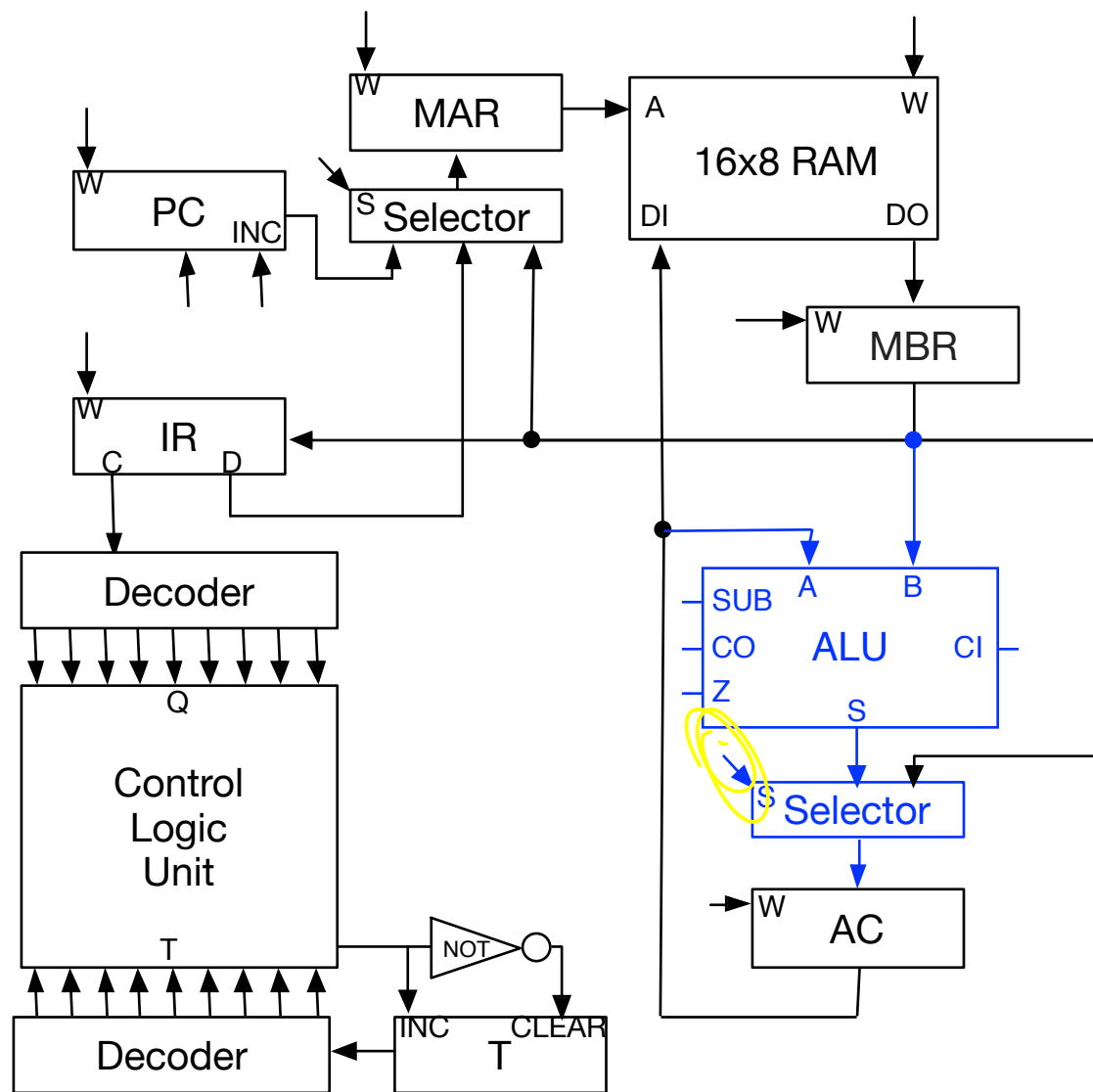
- Store result of ALU operation in accumulator (AC)

$$AC = AC \pm B$$



- Accumulator feeds back into ALU
- Operations are  $AC = AC + B$  or  $AC = AC - B$

# ALU in Circuit





add

# ADD: Add to Accumulator



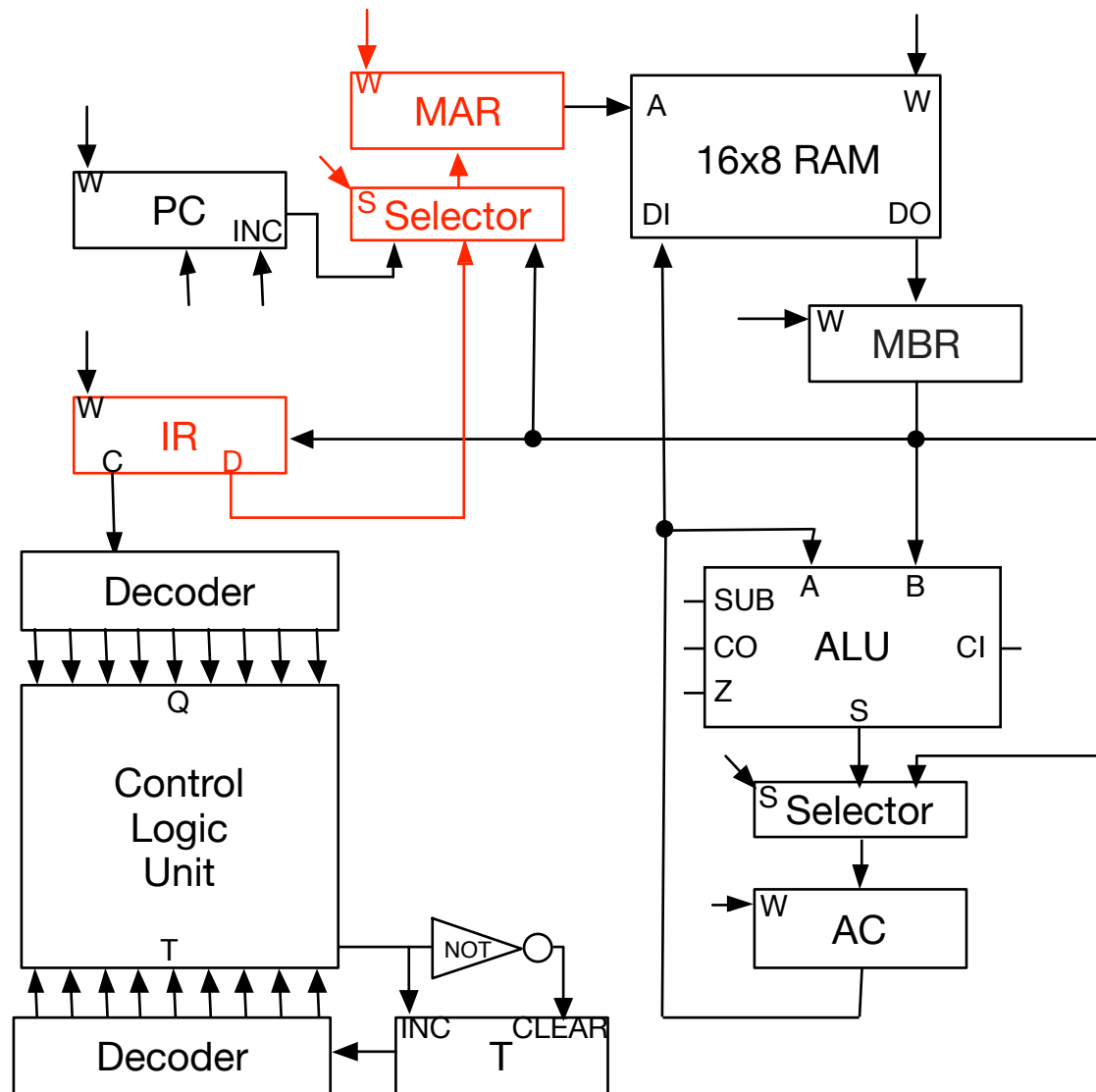
- Add value from memory address to accumulator
- Steps
  - load value of specified memory address
  - use that value as a memory address (second lookup)
  - store value from second lookup into accumulator

# Micro Program for ADD

- Load indirectly into accumulator

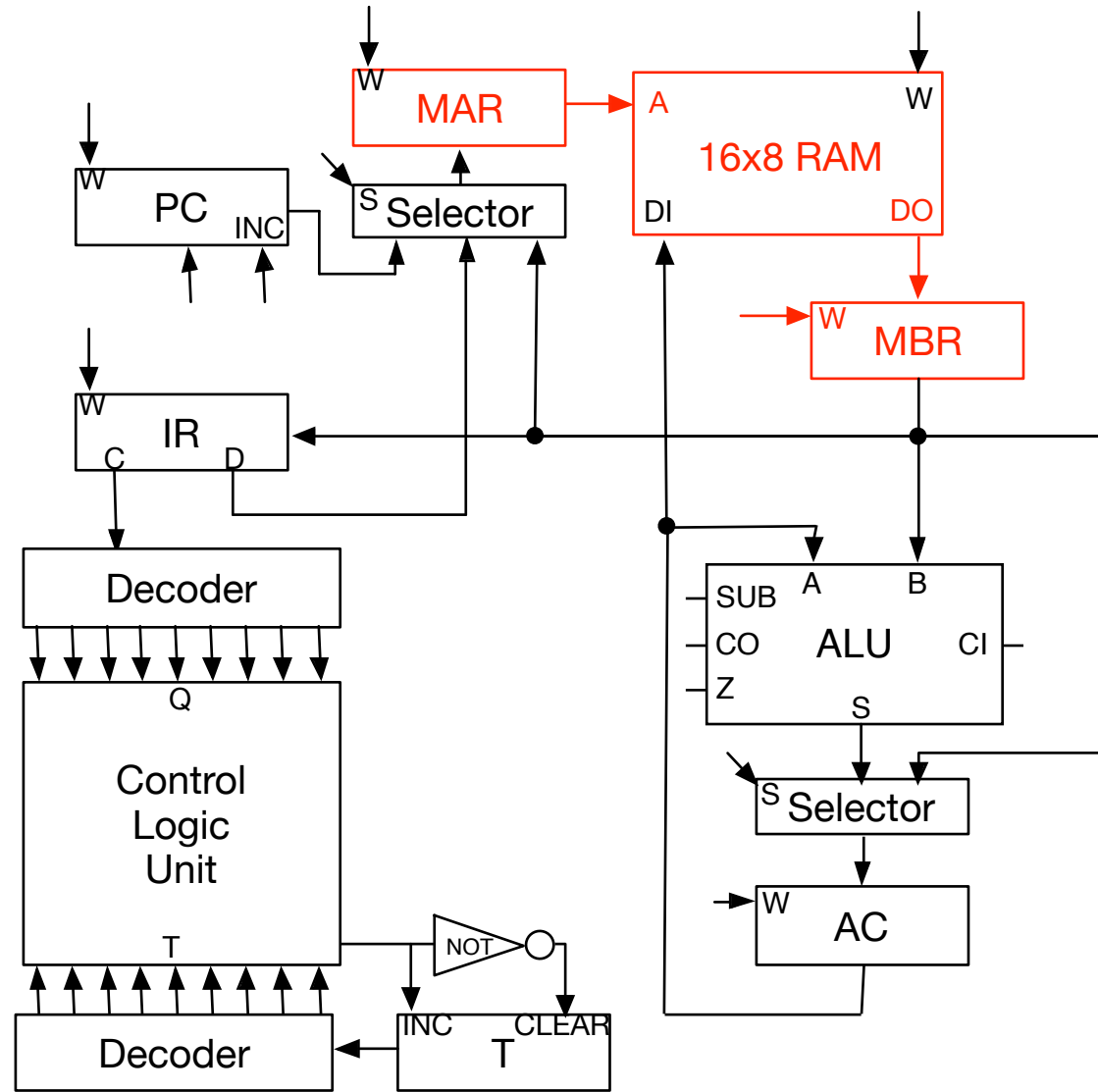
Op Code	Time	Command
q <sub>5</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>5</sub>	t <sub>4</sub>	MBR ← M
q <sub>5</sub>	t <sub>5</sub>	AC ← AC + MBR <del>*</del>

q<sub>5</sub> t<sub>3</sub>: MAR ← IR(D)

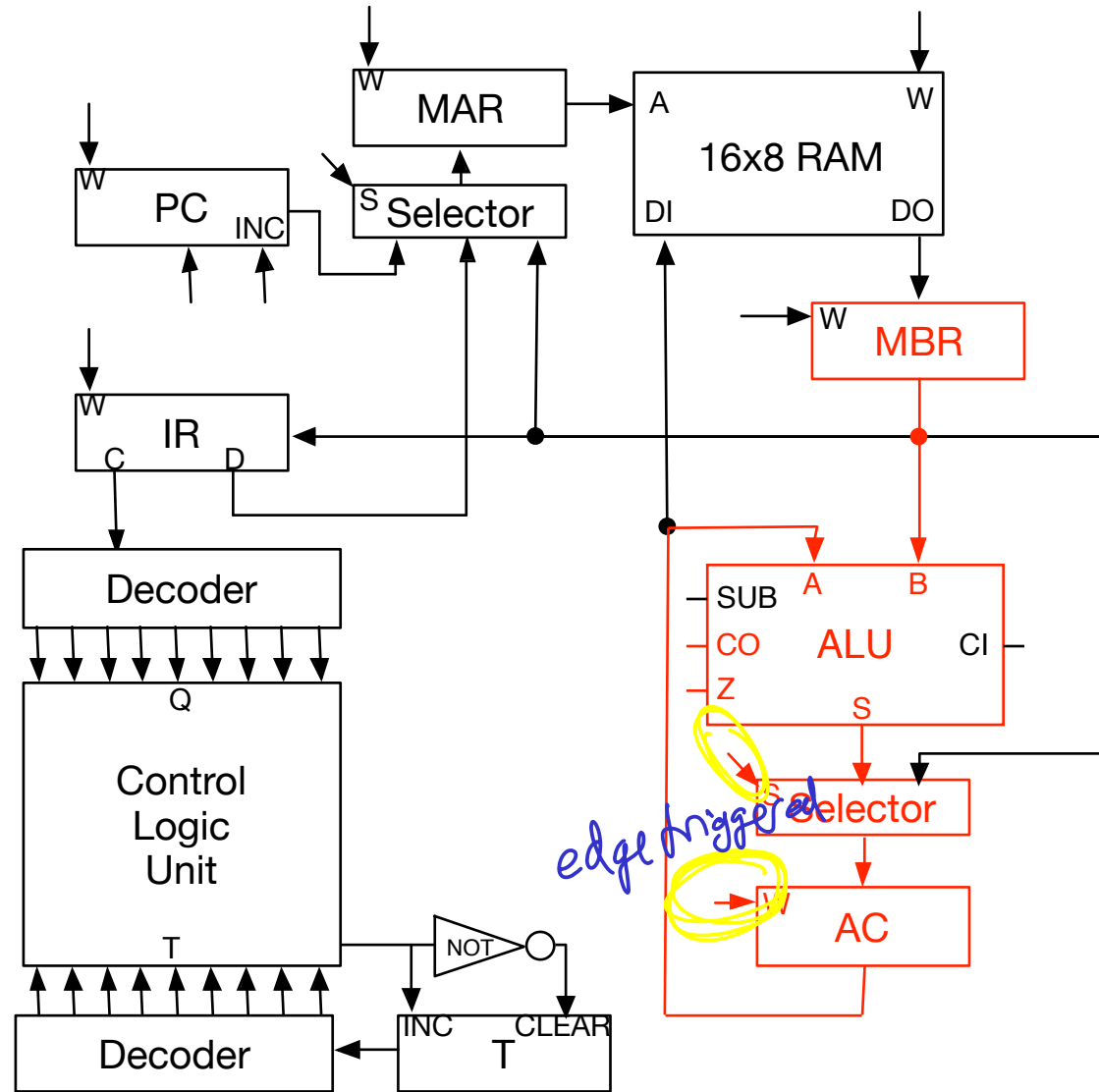




q<sub>5</sub> t<sub>4</sub>: MBR ← M



$q_5 \ t_5: \ AC \leftarrow AC + MBR$





sub

# SUB: Subtract from Accumulator



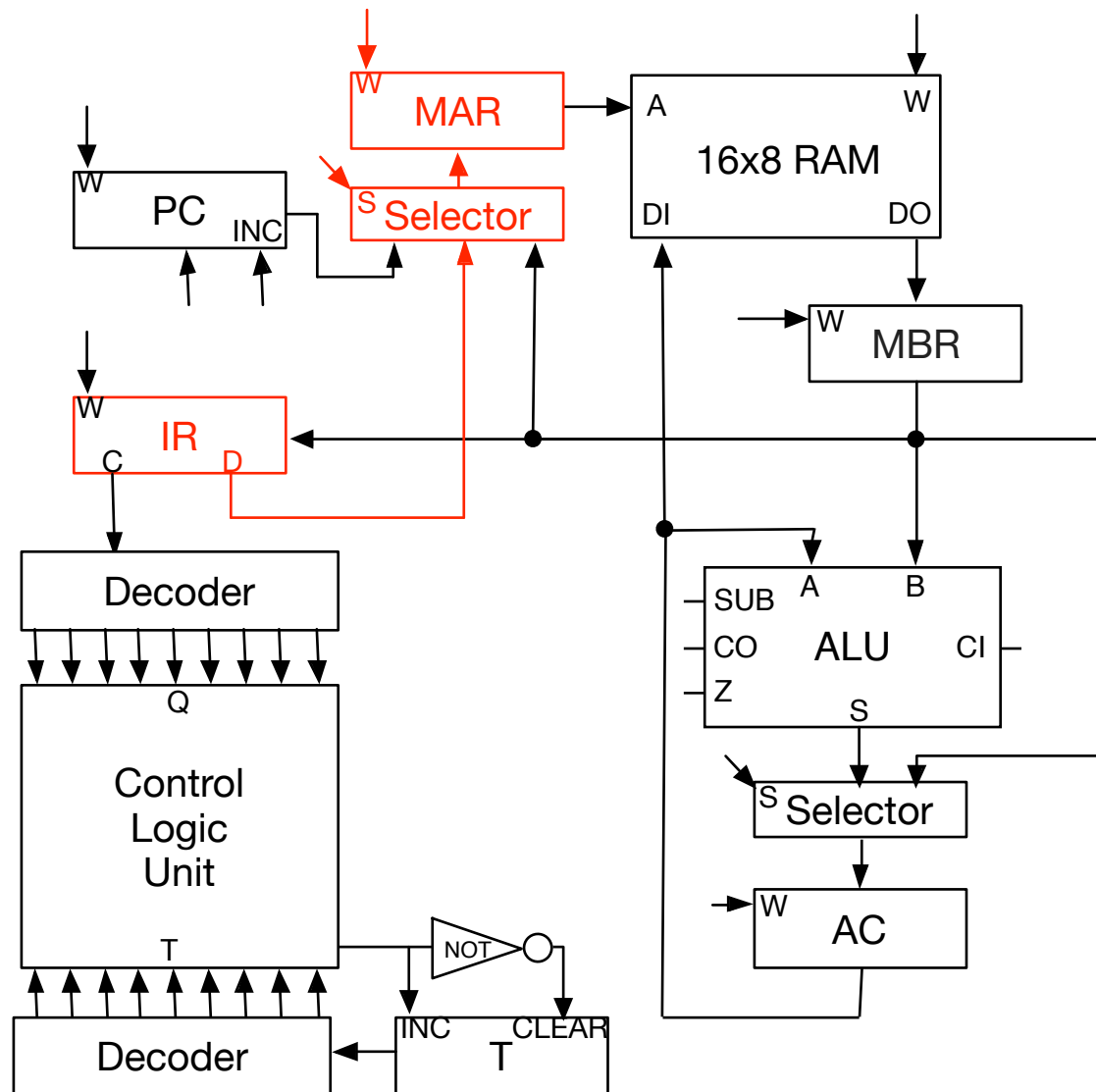
- Subtract from accumulator the value from memory
- Same as ADD, just set subtraction flag of ALU

# Micro Program for SUB

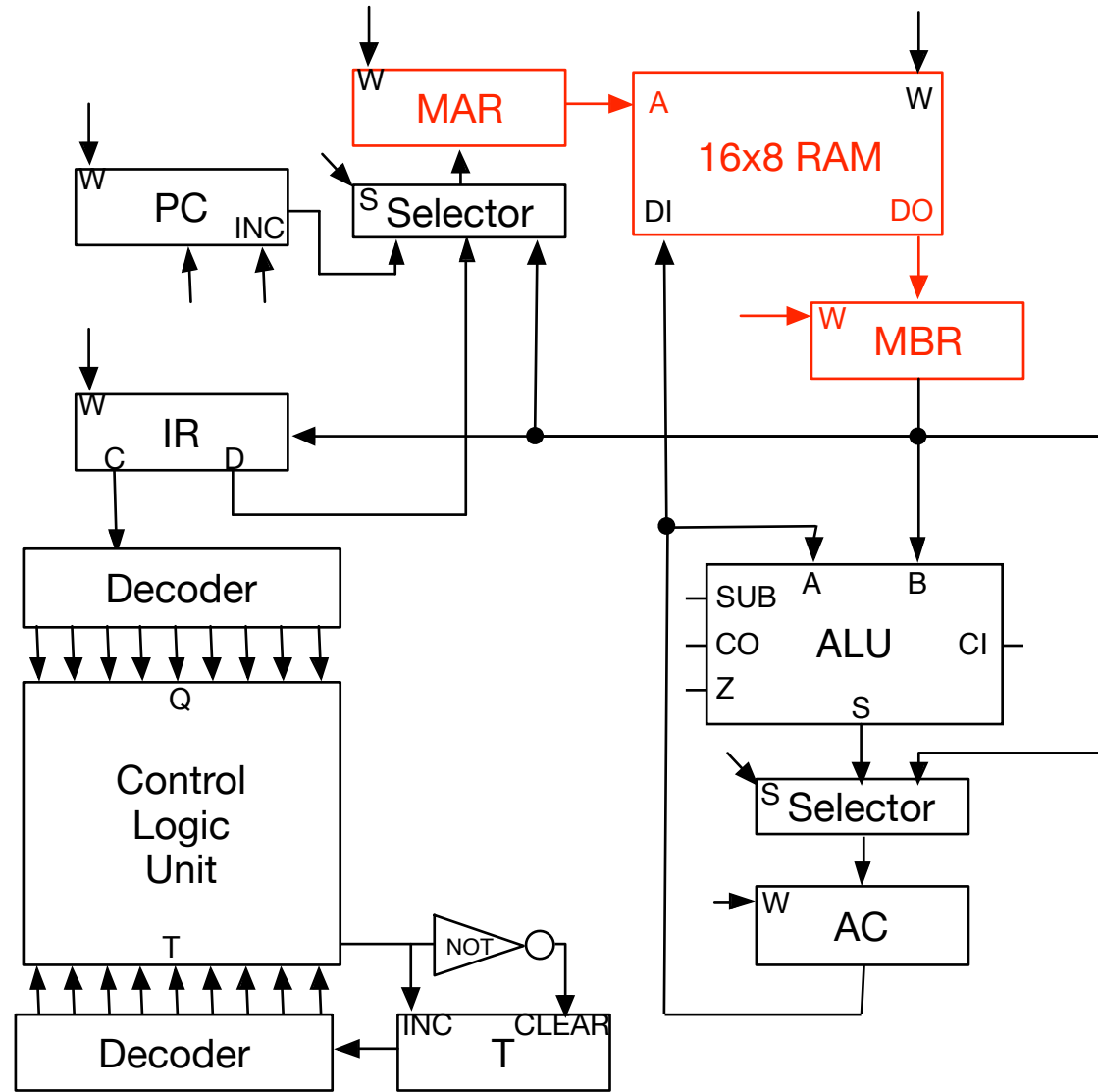
- Load indirectly into accumulator

Op Code	Time	Command
q <sub>5</sub>	t <sub>3</sub>	MAR ← IR(D)
q <sub>5</sub>	t <sub>4</sub>	MBR ← M
q <sub>5</sub>	t <sub>5</sub>	AC ← AC - MBR

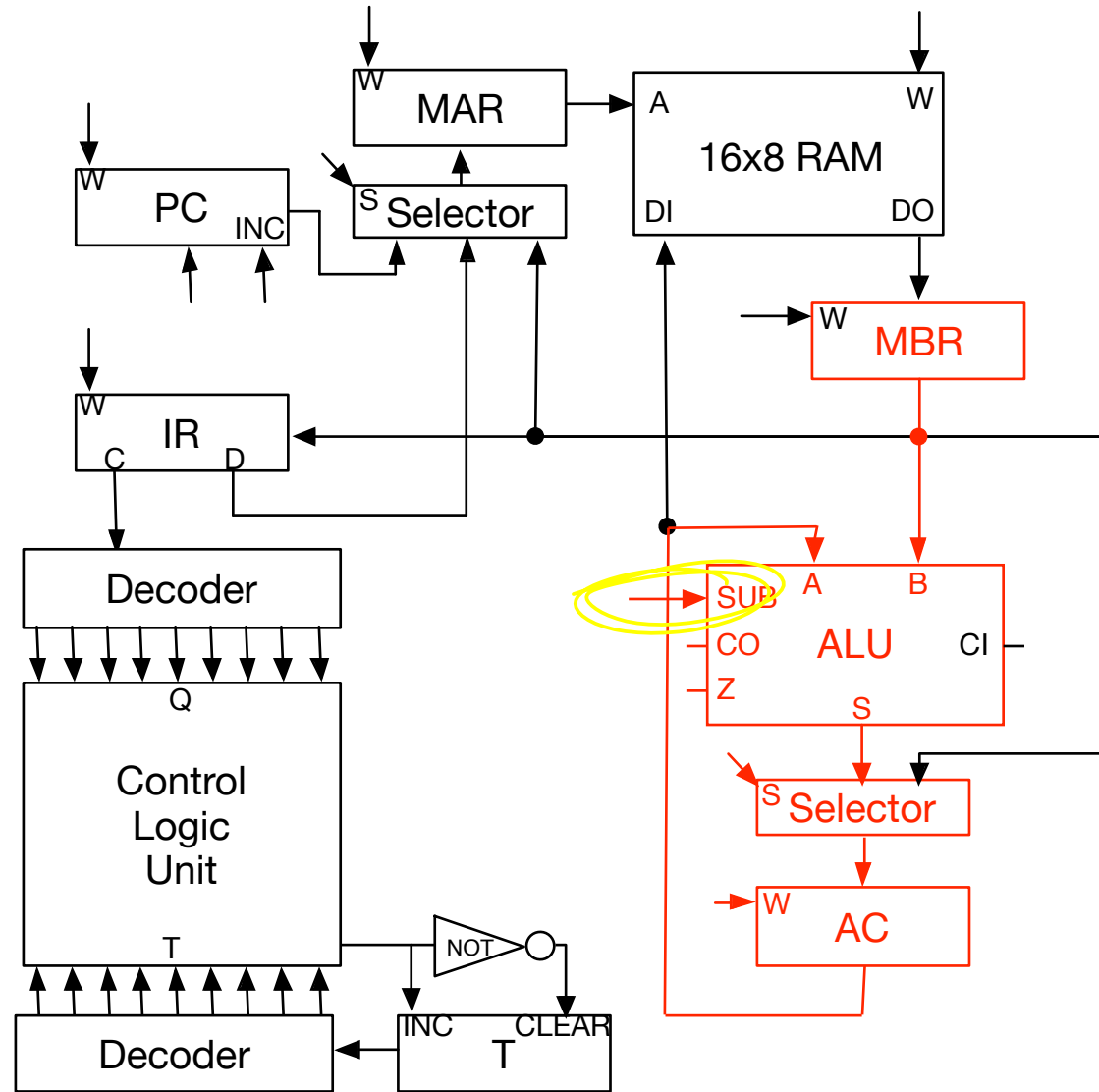
q<sub>5</sub> t<sub>3</sub>: MAR ← IR(D)



q<sub>5</sub> t<sub>4</sub>: MBR ← M



$q_5 \ t_5: \ AC \leftarrow AC \oplus MBR$







**jmp**

# Program Counter (PC)

- Position of the next instruction is stored in program counter
- This gets updated during instruction fetch

Time	Command
$t_0$	$MAR \leftarrow PC$
$t_1$	$MBR \leftarrow M, PC \leftarrow PC + 1$
$t_2$	$IR \leftarrow MBR$
<del><math>t_3</math></del>	<del><math>PC \leftarrow PC + 1</math></del>

# JMP: Jump

- Assign value to position of the next instruction
- Sequencing of micro program
  - instruction fetch (includes program counter inc)
  - command-specific micro instructions
- No problem that program counter gets modified twice

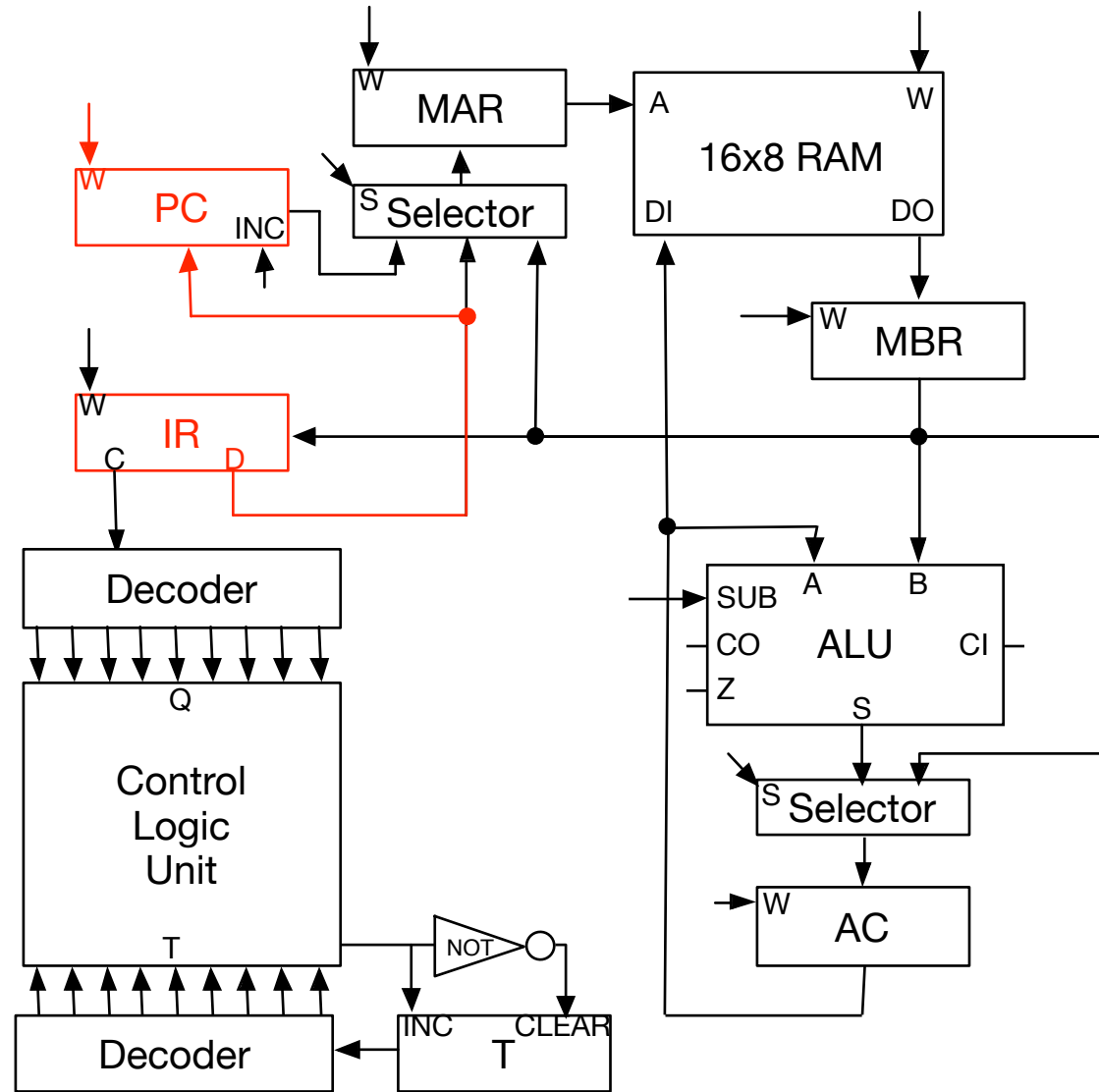
# Micro Program for JMP



- Change program counter to specified address

Op Code	Time	Command
q <sub>7</sub>	t <sub>3</sub>	PC ← IR(D)

# q<sub>7</sub> t<sub>3</sub>: PC ← IR(D)

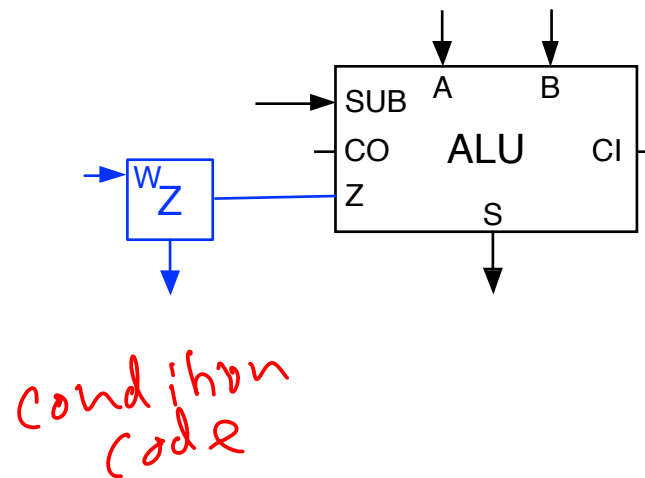




jpz

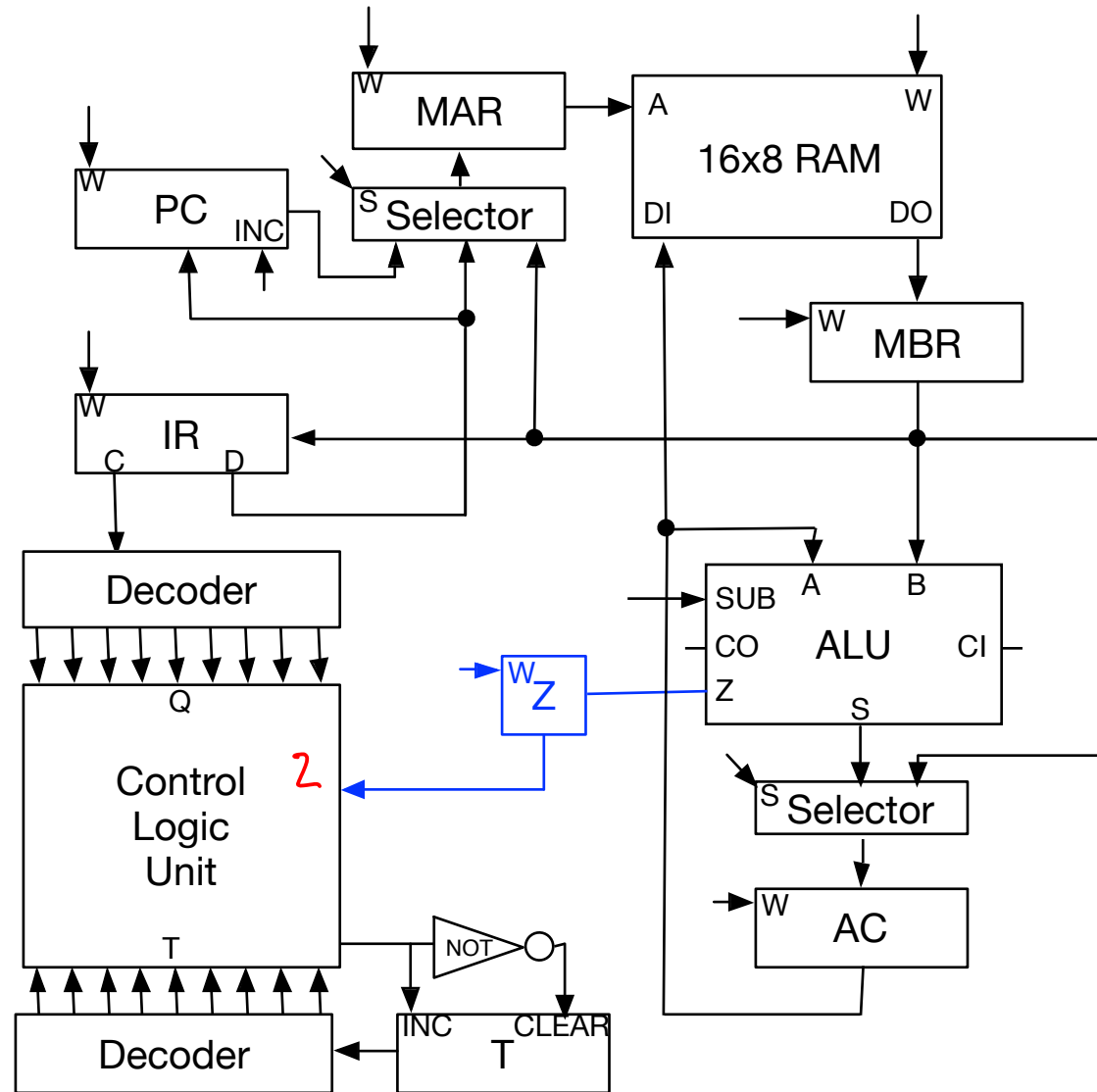
# Zero Flag

- Zero flag
  - set when result of a ALU operation is 0
  - stored in flag





# Z Flag in Circuit





# Micro Program for JPZ

- Z flag is a condition for executing a micro program (same as JMP)

Zero	Op Code	Time	Command
1	q <sub>7</sub>	t <sub>3</sub>	PC ← IR(D)

*Conditional execution*

- If not set, no micro program is executed