Lecture 32: I/O multiplexing

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601.229 Computer Systems Fundamentals



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Example code for today is on course website in iomux.zip



Blocking operations

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Server main loop:

```
int server_fd = open_listenfd(port);
while (1) {
    int client_fd =
        Accept(server_fd, NULL, NULL);
        chat_with_client(client_fd);
        close(client_fd);
}
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Server main loop:

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int server_fd = open_listenfd(port);
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2. Waiting to receive data from client

Server main loop:

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```

The server is not responsive while

- 1. Waiting for client connection to arrive
- 2. Waiting to receive data from client
- 3. Waiting to send data to client (sometimes required by TCP protocol)

Operation such as accept, read, and write can block

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- Problem: while a thread is blocked, it can't do anything else
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- E.g., when calling accept, the calling thread is blocked until a request for a new client connection
- Problem: while a thread is blocked, it can't do anything else
- So, there is no way to support multiple simultaneous clients, and have the server be responsive, using a single thread
 - ► Or is there?

- Modern operating systems support nonblocking I/O
- In Unix/Linux, a file descriptor can be made nonblocking
- All operations that would normally block are guaranteed not to block if the filed descriptor is nonblocking
- If a blocking operation (accept, read, write) is invoked, but it can't be completed immediately:

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- Operation returns an error
- errno is set to EWOULDBLOCK error code

- When a C library or system call function fails, errno is set to an integer error code to indicate the reason for the failure
- Available using #include <errno.h>
- It's not actually a global variable (because that wouldn't work in a multithreaded program)
- Actual definition in the Linux C library (glibc):

```
extern int *_errno_location (void) __THROW __attribute_const__;
# define errno (*__errno_location ())
```

- __errno_location function returns a pointer to an integer variable allocated in thread-local storage
 - So, each thread has its own errno

Could we handle multiple client connections simultaneously as long as the server avoids doing any blocking $\ensuremath{I/O}\xspace$

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Challenge: how do we know which file descriptors are ready to perform I/O?

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I/O multiplexing

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Alternative approach for supporting multiple simultaneous client connections

Basic idea: server maintains sets of active file descriptors (mostly client connections, but also for file $\rm I/O)$

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Main server loop uses select or poll system call to check which file descriptors are *ready*, meaning that a read or write can be performed without blocking

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Basic idea: server maintains sets of active file descriptors (mostly client connections, but also for file $\rm I/O)$

Main server loop uses select or poll system call to check which file descriptors are *ready*, meaning that a read or write can be performed without blocking

Compared to using processes or threads for concurrency:

- Advantage: less overhead (CPU, memory) per client connection than processes or threads
- Disadvantage: higher code complexity

The select system call:

readfds, writefds, and exceptfds are sets of file descriptors

select waits until at least one file descriptor has become ready for reading or writing, or has an exceptional condition

- readfds, writefds, and/or exceptfds are modified to indicate the specific file descriptors that are ready
- timeout specifies maximum amount of time to wait, NULL means indefinitely

An fd_set represents a set of file descriptors

Operations (where set is an fd_set variable):

- FD_ZERO(&set): make set empty
- ► FD_SET(fd, &set): add fd to set
- FD_CLR(fd, &set): remove fd from set
- FD_ISSET(fd, &set): true if fd is in set, false otherwise

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Pseudo-code:

```
create server socket, add to active fd set
while (1) {
```

```
wait for fd to become ready (select or poll)
```

```
if server socket ready
accept a connection, add it to set
```

```
for fd in client connections
    if fd is ready for reading, read and update connection state
    if fs is ready for writing, write and update connection state
}
```

The main difficulty of using I/O multiplexing is that communication with clients is event-driven

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Data read might be a partial message

Similar issue when sending data to client: data might need to be sent in chunks

Maintaining and updating state of client connections is more complicated compared to code for process- or thread-based concurrency

▶ With these approaches, we can just use normal loops and control flow

- Example: echoserv.c
- Protocol: read one line of text from client, send same line back, repeat until quit is received

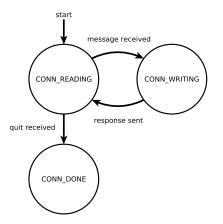
Per-connection data structure: #define CONN_READING 0 #define CONN_WRITING 1 #define CONN_DONE 2 struct Connection { char in_buf[BUFFER_SIZE]; char out_buf[BUFFER_SIZE]; int in_count, out_pos, out_count; int state; };

in_buf, in_count: data received from client
out_buf, out_pos, out_count: data to be sent to client
state: client state (CONN_READING, CONN_WRITING, or CONN_DONE)

A synchronous network protocol can be modeled as a *state machine*

In a protocol implementation using threads or processes for concurrency, state is implicit

When implementing a protocol with I/O multiplexing, state must be explicit



Even when using select or poll to determine when file descriptors are ready, it is still a good idea to make them nonblocking

Avoids situations where an I/O operation might block

```
Making a file descriptor nonblocking:
    void make_nonblocking(int fd) {
      int flags = fcntl(fd, F_GETFL, 0);
      if (flags < 0) {
        fatal("fcntl failed: could not get flags");
      }
      flags |= 0_NONBLOCK;
      if (fcntl(fd, F_SETFL, flags) < 0) {</pre>
        fatal("fcntl failed: could not set flags");
      }
    }
```

- Server has two fd_sets, readfds and writefds
- These specify the file descriptors that the server wants to check for being ready to read (readfds) or write (writefds)
- The server socket and the client file descriptors of all connections in the CONN_READING state are placed in readfds
- The client file descriptors of all connections in the CONN_WRITING state are placed in writefds
- Each call to select determines which file descriptors in readfds are ready for reading, and which file descriptors in writefds are ready for writing
 - If the server socket file descriptor is ready for reading, it means that a connection request has arrived (and a call to accept will not block)

// Code executed for each iteration of server main loop

```
// Place client socket fds in readfds and writefds as appropriate
for (int fd = 0; fd <= maxfd; fd++) {
   struct Connection *conn = client_conn[fd];
   if (conn) {
      if (conn->state == CONN_READING) {
        FD_SET(fd, &readfds);
      } else if (conn->state == CONN_WRITING) {
        FD_SET(fd, &writefds);
      }
   }
}
```

```
// Server socket is always in readfds
FD_SET(serverfd, &readfds);
```

```
int rc = select(maxfd + 1, &readfds, &writefds, NULL, NULL);
if (rc < 0) {
  fatal("select failed");
}
```

The maxfd variable keeps track of the maximum file descriptor value: select is more efficient when it checks fewer file descriptors for readiness

```
if (FD_ISSET(serverfd, &readfds)) {
    int clientfd = Accept(serverfd, NULL, NULL);
    make_nonblocking(clientfd);
    if (clientfd > maxfd) {
        maxfd = clientfd;
    }
      client_conn[clientfd] = create_client_conn();
}
```

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Service client connections

```
for (int fd = 0; fd <= maxfd; fd++) {</pre>
  if (client conn[fd] != NULL) {
    struct Connection *conn = client conn[fd];
    if (FD_ISSET(fd, &readfds)) {
      client do read(fd, conn);
    }
    if (FD ISSET(fd, &writefds)) {
      client do write(fd, conn);
    }
    if (conn->state == CONN DONE) {
      close(fd);
      free(conn);
      client conn[fd] = NULL;
  }
```

```
void client do read(int fd, struct Connection *conn) {
  int remaining = BUFFER_SIZE - conn->in_count - 1;
  ssize_t rc = read(fd, conn->in_buf + conn->in_count, remaining);
 if (rc < 0) {
   fatal("read failed");
  }
  conn->in count += rc;
 // process the data that was read
  ...40+ lines of code omitted...
}
```

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  }
  conn->in count += rc;
 // process the data that was read
  ...40+ lines of code omitted...
}
```

Code is fairly complicated because it must

- Determine if a complete message was received
- If so, copy it to out_buf, deal with leftover data, update connection state

```
void client_do_write(int fd, struct Connection *conn) {
  int remaining = conn->out count - conn->out pos;
  ssize_t rc = write(fd, conn->out_buf + conn->out_pos, (size_t) remaining);
 if (rc < 0) {
   fatal("write failed");
 }
 conn->out_pos += rc;
  if (conn->out_pos == conn->out_count) {
    conn->state = CONN READING;
  }
}
```

```
void client_do_write(int fd, struct Connection *conn) {
  int remaining = conn->out count - conn->out pos;
  ssize_t rc = write(fd, conn->out_buf + conn->out_pos, (size_t) remaining);
 if (rc < 0) {
   fatal("write failed"):
 }
  conn->out_pos += rc;
  if (conn->out_pos == conn->out_count) {
    conn->state = CONN READING;
  }
}
```

Fairly straightforward: just try to copy data from out_buf to the client socket

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► However: the protocol was *very* simple

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- ► **However**: the protocol was *very* simple
 - and even so, client_do_read was quite complicated!

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- ► However: the protocol was *very* simple
 - and even so, client_do_read was quite complicated!
- Real protocols (e.g., HTTP) would be *much* more complicated to implement

- The I/O multiplexing echo server implementation not terribly complex (a little over 200 lines of code)
- ► However: the protocol was *very* simple
 - and even so, client_do_read was quite complicated!
- Real protocols (e.g., HTTP) would be *much* more complicated to implement
- It would be nice if there were a way to get the benefits of I/O multiplexing, but write our code in a "threaded" style rather than an "event-driven" style

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I/O multiplexing with coroutines

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One way to reduce the complexity of I/O multiplexing is to implement communication with clients using *coroutines*

Coroutines are, essentially, a lightweight way of implementing threadsBut with runtime cost closer to function call overhead

Each client connection is implemented as a coroutine

When a client file descriptor finds that a client fd is ready for reading or writing, it *yields* to the client coroutine

Client coroutine will do I/O, and then yield back to the main routine

Echo server implementation with coroutines

- echoserv_co.c is an echo server implementation using coroutines
- Similar number of lines of code as echoserv.c
- ▶ However, 30 lines of code are coroutine-aware versions of read and write
 - They check for EWOULDBLOCK and yield back to the main routine if a call to read or write would block

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- Server main loop is very similar
- Actual protocol implementation is much simpler!

Echo server client coroutine

```
void chat_with_client(void) {
  struct Connection *conn = (struct Connection *) aco get arg();
  for (;;) {
   // read a line
    conn->state = CONN_READING;
    co readline(conn);
    // if line was "quit", we're done
    if (strcmp(conn->out buf, "quit") == 0) {
      break;
    }
    // echo line back to client
    conn->state = CONN WRITING;
    co_write_fully(conn->fd, conn->out_buf, strlen(conn->out_buf));
    co_write_fully(conn->fd, "\r\n", 2);
  }
  aco_exit();
}
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```

- The chat_with_client function looks almost exactly like a thread start function
- The assignments to conn->state help the main routine know when to schedule the coroutine (based on the readiness of its file descriptor for reading or writing)
- The co_readline and co_write_fully functions are "coroutine-aware" I/O functions which yield back to the main routine if a call to read or write would block

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See complete code for details