Lecture 21: Signals

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Example code

Example code for today is on course website in signals.zip

Signals

Signals

- ► Software-level communication between processes
- ► Sending the signal from one process
- ► Receiving the signal by another process
 - ignore
 - terminate
 - catch signal
- ► Handled by kernel

Examples

Number	Name	Default	Corresponding Event
1	SIGHUP	terminate	terminal line hangup
2	SIGINT	terminate	interrupt from keyboard
3	SIGQUIT	terminate	quit from keyboard
4	SIGILL	terminate	illegal instruction
5	SIGTRAP	terminate & dump core	trace trap
9	SIGKILL	terminate*	kill process
18	SIGCONT	ignore	continue process if stopped
19	SIGSTOP	stop until SIGCONT*	stop signal not from terminal
20	SIGTSTP	stop until SIGCONT	stop signal from terminal

^{* =} SIGKILL and SIGSTOP cannot be caught



Sending Signals

- ► From shell with command
 - \$ /bin/kill -9 2423
- ► From shell with keystroke to running process
 - \$ start-my-process
 CTRL+C
 - ► CTRL+C: sends SIGINT
 - ► CTRL+Z: sends SIGTSTP
- ▶ There is also a C function and an Assembly syscall

Receiving Signals

- ▶ When kernel about to continue process, checks for signals
- ▶ If there is a signal, forces process to receive signal
- ► Each signal has a default action
 - ignore
 - terminate
 - terminate and dump core
 - ▶ stop
- ▶ Process can also set up a signal handler for customized response

Signal Handler

Signal handler in C #include "csapp.h" void sigint handler(int sig) { printf("Caught SIGINT\n"); exit(0); int main() { signal(SIGINT, sigint handler); pause(); return 0;

▶ Now, process writes "Caught SIGINT" to stdout before terminating

Signal delivery, signal masks

Signal delivery

- ▶ In general, the OS kernel could deliver a signal to a process at any time
- ▶ Delivering a signal:
 - Pushing a special return address of code to restore the CPU state (so that process can continue normal execution when signal handler returns)
 - Creating stack frame for signal handler
 - Setting argument registers for signal handler
 - ► Jumping to signal handler
- Signals are normally delivered on the process's call stack
 - ► Really a *thread*'s call stack, more about threads later on
- Process may designate a special area of memory to serve as a stack for received signals

Signals and asynchrony

- ► Signal delivery could occur before or after *any* instruction
- ► That means that signals are asynchronous
- "Asynchronous" means "could happen at any time" or "ordering is unpredictable"
- ▶ Signal handlers are asynchronous with respect to the rest of the program
- ▶ This can cause strange behavior!

A C program

```
#include "csapp.h"

#define NCOUNT 100000000

volatile int count = 0;

int main(void) {
    // count up
    for (int i = 0; i < NCOUNT; i++) { count++; }
    printf("count=%d\n", count);
    return 0;
}</pre>
```

Note that "volatile" tells the compiler not to optimize away accesses to the count variable

Compiling and executing the program

```
$ gcc -0 -Wall -c count.c
$ gcc -o count count.o
$ ./count
count=100000000
```

Nothing surprising happened

Interval timers

- ► An *interval timer* is a means for notifying the process than an interval of time has elapsed
- ► Can be "one shot" or repeating
- ▶ The setitimer system call allows the process to create an interval timer
- When the timer elapses, OS kernel sends SIGALRM signal to process
- ► Let's change the program so that the handler for SIGALRM is also incrementing the global counter

Modified version of program

```
#include "csapp.h"
#define NCOUNT 100000000
volatile int stop = 0, nsigs = 0, count = 0;
void sigalrm_handler(int signo) {
  if (!stop) { nsigs++; count++; }
int main(void) {
  // handle SIGALRM signal
  code to set up signal handler for SIGALRM
  // arrange for SIGALRM to be delivered once every millisecond
  code to set up interval timer
  // count up
  for (int i = 0; i < NCOUNT; i++) { count++; }</pre>
  code to check final counts
  return 0;
```

Code to set up signal handler

```
// code to set up signal handler for SIGALRM
struct sigaction sa;
sigemptyset(&sa.sa_mask);
sa.sa_flags = 0;
sa.sa_handler = sigalrm_handler;
sigaction(SIGALRM, &sa, NULL);
```

Note that to install a signal handler, sigaction is recommended over signal, for reasons we'll discuss soon

Using setitimer

```
// code to set up interval timer
struct itimerval itv;
itv.it_interval.tv_sec = 0;
itv.it_interval.tv_usec = 1000; // 1000 microseconds = 1 millisecond
itv.it_value = itv.it_interval;
setitimer(ITIMER_REAL, &itv, NULL);
```

ITIMER_REAL means that the intervals are "real time" (not relative to CPU time used by the process)

Does the final count make sense?

In theory, the final value of count should be <code>NCOUNT</code> + <code>nsigs</code>

- ▶ NCOUNT is the number of increments (to count) in main
- nsigs is the number of calls to the signal handler (which also increments count)

Running the modified program

```
$ gcc -0 -Wall -c alarm1.c
$ gcc -o alarm1 alarm1.o
$ ./alarm1
count=100000028, NCOUNT=100000000, nsigs=174
anomaly detected!
```

What just happened?

Asynchrony and atomicity

- ▶ When a program
 - ▶ has code paths which execute asynchronously, and
 - ► the asynchronous paths update shared data then anomalous behavior can be observed if either process executes code which is not *atomic*
- ► "Atomic" means "happens in its entirety, or not at all"
- ► Incrementing a variable is not (necessarily) atomic

Why increment is not atomic

▶ The statement count++; really means

```
1: tmp = count;

2: tmp = tmp + 1;

3: count = tmp;

where tmp is a register
```

- ► If count is updated by code executing asynchronously, the updated value could be overwritten by step 3
- ► The anomaly in our program execution shows this happening (the final value of count doesn't reflect all of the increments)

Zoom poll!

Assume:

- count is a global variable whose initial value is 0
- ▶ tmp and tmp2 are registers

Also, assume the following two sequences of operations are executed asynchronously:

```
// sequence 1 // sequence 2
tmp = count; tmp2 = count;
tmp = tmp + 1; tmp2 = tmp2 + 1;
count = tmp; count = tmp2;
```

After both sequence 1 and sequence 2 complete, what are the possible final values of count?

- A. 0
- B. 1
- C. 2
- D. Either 1 or 2
- E. Either 0, 1, or 2

Synchronization, signal masks

- "Synchronization" means coordinating asynchronous accesses to shared data to avoid anomalous results
- ► For programs using signals we can use *signal masks* to synchronize signal handlers with the main program
- ► Signal mask = set of signals that are temporarily blocked
 - OS kernel will only deliver a signal if it isn't blocked
 - Note that not all signals may be blocked
 - ► For our example program, we can block SIGALRM to avoid the signal handler from executing at the wrong time

Modified main loop

```
sigset_t mask;
sigemptyset(&mask);
sigaddset(&mask, SIGALRM);

// count up
for (int i = 0; i < NCOUNT; i++) {
   sigprocmask(SIG_BLOCK, &mask, NULL);
   count++;
   sigprocmask(SIG_UNBLOCK, &mask, NULL);
}</pre>
```

Running the modified program

```
$ gcc -0 -Wall -c alarm2.c
$ gcc -o alarm2 alarm2.o
$ ./alarm2
count=100070462, NCOUNT=100000000, nsigs=70462
  count makes sense
```

No anomaly! However, note that the program took a very long time to run (more than 70 seconds) due to the overhead of calling sigprocmask in the main loop.

signal vs. sigaction

- ► Historically, the signal system call was used to register a signal handler on Unix systems
- ► New code should use sigaction
- ► Why?
 - ► Handlers registered using signal may get "unregistered" when the signal arrives
 - signal doesn't provide any mechanism for preventing signal handlers from being interrupted by other signals